

Pre-nominated Session SM26

Vehicle dynamics

Co-Chair(s): S. Iwnicki (UK)
 R. Sharp (UK)

Paper ID	Title	Authors
SM26L_10701	Optimal Path Following Road Vehicle Steering Control	Robin S. Sharp
SM26L_10909	Simulation and Testing of a Wheelset with Induction Motor Driven Independent Wheels	B. Liang, S. D. Iwnicki, F. J. Swift
SM26L_11589	Railway Vehicle Simulation Using Non - Elliptical Wheel - Rail Contact Model	Vladislav Yazykov, Dmitry Pogorelov, Georgy Mikhailchenko
SM26L_11672	A Modelling Technique for Fast Computer Simulations of Configurable Vehicle Systems	Georg Rill, Cornelius Chucholowski
SM26L_11795	Experimental and Theoretical Aanalysis of Freight Wagon Link Suspension	Per - Anders Joensson, Sebastian Stichel
SM26L_11832	Mathematical Models and Simulation of Stick - Slip Processes in a Car Steering System	Zbigniew Lozia, Dariusz Zardecki