

# The Derivation of Navier-Stokes Equations in Spherical Coordinates

S.P. Kiselev, E.V. Vorozhtsov, and V.M. Fomin

## ■ Impressum

This Mathematica-Notebook is part of the book entitled

S.P. Kiselev, E.V. Vorozhtsov, and V.M. Fomin  
Foundations of Fluid Mechanics with Applications  
Problem Solving Using *Mathematica*.  
Birkhauser Boston, Basel, 1999.

## ■ Copyright

Foundations of Fluid Mechanics with Applications  
Problem Solving Using *Mathematica*.  
■ Birkhauser Boston, Basel, 1999.

## ■ General Description

This Notebook enables the user to compute the analytic expressions for the components of the velocity Laplacian  $\mathbf{Dv}$  in the spherical coordinates  $r, \mathbf{j}, \mathbf{q}$ .

The discussion of underlying formulas may be found in Section 5.1 of the above book.

## ■ User's Guide

### ■ Step 1

Compile the program cell entitled "TheDefinition of Spherical Coordinates"  
(see the Section "Program Listing").

## ■ Step 2

Compile the program cell entitled "The Partial Derivatives  $\partial_x x_m$ ,  $i, m = 1, 2, 3$ ."  
(see the Section "Program Listing").

## ■ Step 3

Compile the program cell entitled "The Expressions for Metric Tensor Components"  
(see the Section "Program Listing").

## ■ Step 4

Compile the program cell entitled "The Continuity Equation"  
(see the Section "Program Listing").

## ■ Step 5

Compile the program cell entitled "The Laplace Operator in the Momentum Equations"  
(see the Section "Program Listing").

## ■ Program Listing

### ■ The Definition of Spherical Coordinates

The quantities  $x[1]$ ,  $x[2]$ ,  $x[3]$  are the Cartesian coordinates;  
the quantities  $k[1]$ ,  $k[2]$ ,  $k[3]$  are the spherical coordinates.

```
x[1] = k[1] Sin[k[2]] Cos[k[3]];
x[2] = k[1] Sin[k[2]] Sin[k[3]];
x[3] = k[1] Cos[k[2]];
```

### ■ The Partial Derivatives $\partial_\xi x_m$ , $i, m = 1, 2, 3$ .

```
g = IdentityMatrix[3];
Do[ Do[ g0 = Sum[D[x[m],k[i]]*D[x[m],k[j]],{m, 3}];
g = ReplacePart[g, g0, {i,j}], {i, 3}], {j, 3}]
```

## ■ The Expressions for Metric Tensor Components

```
Do[Do[gj = g[[i, j]] /. {k[1] -> r, k[2] -> q, k[3] -> j};
gj = TrigExpand[TrigReduce[gj]] /. {Cos[q]^2 -> 1 - Sin[q]^2};
g = ReplacePart[g, Expand[gj], {i, j}], {j, 3}], {i, 3}];
Print["g = ", TraditionalForm[MatrixForm[g]]];
```

$$g = \begin{pmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2(q) \end{pmatrix}$$

## ■ The Continuity Equation

```
g1 = g[[1, 1]]; g2 = g[[2, 2]]; g3 = g[[3, 3]];
den = PowerExpand[(g1 g2 g3)^(1/2)];
div = 1 / den
(∂r (PowerExpand[(g2 g3)^(1/2)] v1[r, Q, j]) + D[PowerExpand[(g1 g3)^(1/2)] v2[r, Q, j], q] +
∂j (PowerExpand[(g1 g2)^(1/2)] v3[r, Q, j])) ;
div = Expand[div] // Simplify;
Print[TraditionalForm[div], " = 0"];
```

$$\frac{1}{r} \left( 2 v_1[r, Q, j] + \cot(q) v_2[r, Q, j] + \csc(q) v_3^{(0,0,1)}(r, Q, j) + r v_1^{(1,0,0)}(r, Q, j) \right) = 0$$

## ■ The Laplace Operator in the Momentum Equations

```

laplace[k_] :=
  (b[1] = g[[1, 1]]; b[2] = g[[2, 2]];
  b[3] = g[[3, 3]]; i = k + 1;
  If[i > 3, i = 1]; j = 6 - i - k;
  r11 = {r -> p[1], q -> p[2], j -> p[3]};
  b[1] = b[1] /. r11; b[2] = b[2] /. r11; b[3] = b[3] /. r11;
  den = PowerExpand[(b[1] b[2] b[3])1/2];
  s1 = D[PowerExpand[(b[j] b[k])1/2] * u[p[1], p[2], p[3], i], p[i]];
  s2 = D[PowerExpand[(b[i] b[k])1/2] * u[p[1], p[2], p[3], j], p[j]];
  s3 = D[PowerExpand[(b[i] b[j])1/2] * u[p[1], p[2], p[3], k], p[k]];
  s4 = D[PowerExpand[(b[j] / (b[i] * b[k]))1/2] *
    D[PowerExpand[b[i]1/2] * u[p[1], p[2], p[3], i], p[k]], p[i]];
  s5 = D[PowerExpand[(b[j] / (b[i] * b[k]))1/2] *
    D[PowerExpand[b[k]1/2] * u[p[1], p[2], p[3], k], p[i]], p[i]];
  s6 = D[PowerExpand[(b[i] / (b[j] * b[k]))1/2] *
    D[PowerExpand[b[k]1/2] * u[p[1], p[2], p[3], k], p[j]], p[j]];
  s7 = D[PowerExpand[(b[i] / (b[j] * b[k]))1/2] *
    D[PowerExpand[b[j]1/2] * u[p[1], p[2], p[3], j], p[k]], p[j]];
  (* invr = {p[1] -> r, p[2] -> q, p[3] -> j} *)
  lap = (1 / PowerExpand[b[k]1/2]) * D[(1 / den) * (s1 + s2 + s3), p[k]] -
    (1 / PowerExpand[(b[i] * b[j])1/2]) * (s4 - s5 - s6 + s7);
  p[1] = r; p[2] = q; p[3] = j;
  lap = Expand[lap] // Simplify;
  lap);
laplace[1]
laplace[2]
laplace[3]

```

$$\frac{1}{r^2} (-2 u[r, q, j, 1] - 2 \cot[q] u[r, q, j, 2] - 2 \csc[q] u^{(0,0,1,0)}[r, q, j, 3] + \csc[q]^2 u^{(0,0,2,0)}[r, q, j, 1] + \cot[q] u^{(0,1,0,0)}[r, q, j, 1] - 2 u^{(0,1,0,0)}[r, q, j, 2] + u^{(0,2,0,0)}[r, q, j, 1] + 2 r u^{(1,0,0,0)}[r, q, j, 1] + r^2 u^{(2,0,0,0)}[r, q, j, 1])$$

$$\frac{1}{r^2} (-\csc[q]^2 u[r, q, j, 2] - 2 \cot[q] \csc[q] u^{(0,0,1,0)}[r, q, j, 3] + \csc[q]^2 u^{(0,0,2,0)}[r, q, j, 2] + 2 u^{(0,1,0,0)}[r, q, j, 1] + \cot[q] u^{(0,1,0,0)}[r, q, j, 2] + u^{(0,2,0,0)}[r, q, j, 2] + 2 r u^{(1,0,0,0)}[r, q, j, 2] + r^2 u^{(2,0,0,0)}[r, q, j, 2])$$

$$\frac{1}{r^2} (-\csc[q]^2 u[r, q, j, 3] + 2 \csc[q] u^{(0,0,1,0)}[r, q, j, 1] + 2 \cot[q] \csc[q] u^{(0,0,1,0)}[r, q, j, 2] + \csc[q]^2 u^{(0,0,2,0)}[r, q, j, 3] + \cot[q] u^{(0,1,0,0)}[r, q, j, 3] + u^{(0,2,0,0)}[r, q, j, 3] + 2 r u^{(1,0,0,0)}[r, q, j, 3] + r^2 u^{(2,0,0,0)}[r, q, j, 3])$$

## ■ The Structure of the Output

The following results are obtained with the aid of the above program:

- (1) the expression for the metric tensor  $g$  in the form of a  $3 \times 3$  matrix;
- (2) the analytic expression for the continuity equation in spherical coordinates;
- (3) the expression for the Laplacian operator in the momentum equation for the velocity component  $v_r$ ;
- (4) the expression for the Laplacian operator in the momentum equation for the velocity component  $v_\theta$ ;
- (5) the expression for the Laplacian operator in the momentum equation for the velocity component  $v_\phi$ .