

Chapter 2

The individual risk model

If the automobile had followed the same development cycle as the computer, a Rolls-Royce would today cost \$100, get a million miles per gallon, and explode once a year, killing everyone inside — Robert X. Cringely

2.1 Introduction

In this chapter we focus on the distribution function of the total claim amount S for the portfolio of an insurer. We are not merely interested in the expected value and the variance of the insurer's random capital, but we also want to know the probability that the amounts paid exceed a fixed threshold. The distribution of the total claim amount S is also necessary to be able to apply the utility theory of the previous chapter. To determine the value-at-risk at, say, the 99.5% level, we need also good approximations for the inverse of the cdf, especially in the far tail. In this chapter we deal with models that still recognize the individual, usually different, policies. As is done often in non-life insurance mathematics, the time aspect will be ignored. This aspect is nevertheless important in disability and long term care insurance. For this reason, these types of insurance are sometimes considered life insurances.

In the insurance practice, risks usually cannot be modeled by purely discrete random variables, nor by purely continuous random variables. For example, in liability insurance a whole range of positive amounts can be paid out, each of them with a very small probability. There are two exceptions: the probability of having no claim, that is, claim size 0, is quite large, and the probability of a claim size that equals the maximum sum insured, implying a loss exceeding that threshold, is also not negligible. For expectations of such mixed random variables, we use the Riemann-Stieltjes integral as a notation, without going too deeply into its mathematical aspects. A simple and flexible model that produces random variables of this type is a mixture model, also called an 'urn-of-urns' model. Depending on the outcome of one drawing, resulting in one of the events 'no claim or maximum claim' or 'other claim', a second drawing is done from either a discrete distribution, producing zero or the maximal claim amount, or a continuous distribution. In the sequel, we present some examples of mixed models for the claim amount per policy.

Assuming that the risks in a portfolio are independent random variables, the distribution of their sum can be calculated by making use of convolution. Even with the computers of today, it turns out that this technique is quite laborious, so

there is a need for other methods. One of the alternative methods is to make use of moment generating functions (mgf) or of related transforms like characteristic functions, probability generating functions (pgf) and cumulant generating functions (cgf). Sometimes it is possible to recognize the mgf of a sum of independent random variables and consequently identify the distribution function. And in some cases we can fruitfully employ a technique called the *Fast Fourier Transform* to reconstruct the density from a transform.

A totally different approach is to compute approximations of the distribution of the total claim amount S . If we consider S as the sum of a ‘large’ number of random variables, we could, by virtue of the Central Limit Theorem, approximate its distribution by a normal distribution with the same mean and variance as S . We will show that this approximation usually is not satisfactory for the insurance practice. Especially in the tails, there is a need for more refined approximations that explicitly recognize the substantial probability of large claims. More technically, the third central moment of S is usually greater than 0, while for the normal distribution it equals 0. We present an approximation based on a translated gamma random variable, as well as the normal power (NP) approximation. The quality of these approximations is similar. The latter can be calculated directly by means of a $N(0, 1)$ table, the former requires using a computer.

Another way to approximate the individual risk model is to use the collective risk models described in the next chapter.

2.2 Mixed distributions and risks

In this section, we discuss some examples of insurance risks, that is, the claims on an insurance policy. First, we have to slightly extend the set of distribution functions we consider, because purely discrete random variables and purely continuous random variables both turn out to be inadequate for modeling the risks.

From the theory of probability, we know that every function $F(\cdot)$ that satisfies

$$\begin{aligned} F(-\infty) &= 0; & F(+\infty) &= 1 \\ F(\cdot) &\text{ is non-decreasing and right-continuous} \end{aligned} \quad (2.1)$$

is a cumulative distribution function (cdf) of some random variable, for example of $F^{-1}(U)$ with $U \sim \text{uniform}(0, 1)$, see Section 3.9.1 and Definition 5.6.1. If $F(\cdot)$ is a step function, that is, a function that is constant outside a denumerable set of discontinuities (steps), then $F(\cdot)$ and any random variable X with $F(x) = \Pr[X \leq x]$ are called *discrete*. The associated probability density function (pdf) represents the height of the step at x , so

$$f(x) = F(x) - F(x-0) = \Pr[X = x] \quad \text{for all } x \in (-\infty, \infty). \quad (2.2)$$

Here, $F(x-0)$ is shorthand for $\lim_{\varepsilon \downarrow 0} F(x-\varepsilon)$; $F(x+0) = F(x)$ holds because of right-continuity. For all x , we have $f(x) \geq 0$, and $\sum_x f(x) = 1$ where the sum is taken over the denumerable set of all x with $f(x) > 0$.

Another special case is when $F(\cdot)$ is *absolutely continuous*. This means that if $f(x) = F'(x)$, then

$$F(x) = \int_{-\infty}^x f(t) dt. \quad (2.3)$$

In this case $f(\cdot)$ is called the probability density function, too. Again, $f(x) \geq 0$ for all x , while now $\int f(x) dx = 1$. Note that, just as is customary in mathematical statistics, this notation without integration limits represents the *definite* integral of $f(x)$ over the interval $(-\infty, \infty)$, and not just an arbitrary antiderivative, that is, any function having $f(x)$ as its derivative.

In statistics, almost without exception random variables are either discrete or continuous, but this is definitely not the case in insurance. Many distribution functions to model insurance payments have continuously increasing parts, but also some positive steps. Let Z represent the payment on some contract. There are three possibilities:

1. The contract is claim-free, hence $Z = 0$.
2. The contract generates a claim that is larger than the maximum sum insured, say M . Then, $Z = M$.
3. The contract generates a ‘normal’ claim, hence $0 < Z < M$.

Apparently, the cdf of Z has steps in 0 and in M . For the part in-between we could use a discrete distribution, since the payment will be some integer multiple of the monetary unit. This would produce a very large set of possible values, each of them with a very small probability, so using a continuous cdf seems more convenient. In this way, a cdf arises that is neither purely discrete, nor purely continuous. In Figure 2.2 a diagram of a mixed continuous/discrete cdf is given, see also Exercise 1.4.1.

The following urn-of-urns model allows us to construct a random variable with a distribution that is a mixture of a discrete and a continuous distribution. Let I be an *indicator random variable*, with values $I = 1$ or $I = 0$, where $I = 1$ indicates that some event has occurred. Suppose that the probability of the event is $q = \Pr[I = 1]$, $0 \leq q \leq 1$. If $I = 1$, in the second stage the claim Z is drawn from the distribution of X , if $I = 0$, then from Y . This means that

$$Z = IX + (1 - I)Y. \quad (2.4)$$

If $I = 1$ then Z can be replaced by X , if $I = 0$ it can be replaced by Y . Note that we may act as if not just I and X, Y are independent, but in fact the triple (X, Y, I) ; only the conditional distributions of $X | I = 1$ and of $Y | I = 0$ are relevant, so we can take for example $\Pr[X \leq x | I = 0] = \Pr[X \leq x | I = 1]$ just as well. Hence, the cdf of Z can be written as

$$\begin{aligned}
F(z) &= \Pr[Z \leq z] \\
&= \Pr[Z \leq z, I = 1] + \Pr[Z \leq z, I = 0] \\
&= \Pr[X \leq z, I = 1] + \Pr[Y \leq z, I = 0] \\
&= q\Pr[X \leq z] + (1 - q)\Pr[Y \leq z].
\end{aligned} \tag{2.5}$$

Now, let X be a discrete random variable and Y a continuous random variable. From (2.5) we get

$$F(z) - F(z - 0) = q\Pr[X = z] \quad \text{and} \quad F'(z) = (1 - q)\frac{d}{dz}\Pr[Y \leq z]. \tag{2.6}$$

This construction yields a cdf $F(z)$ with steps where $\Pr[X = z] > 0$, but it is not a step function, since $F'(z) > 0$ on the support of Y .

To calculate the moments of Z , the moment generating function $E[e^{tZ}]$ and the stop-loss premiums $E[(Z - d)_+]$, we have to calculate the expectations of functions of Z . For that purpose, we use the iterative formula of conditional expectations, also known as the law of total expectation, the law of iterated expectations, the tower rule, or the smoothing theorem:

$$E[W] = E[E[W | V]]. \tag{2.7}$$

We apply this formula with $W = g(Z)$ for an appropriate function $g(\cdot)$ and replace V by I . Then, introducing $h(i) = E[g(Z) | I = i]$, we get, using (2.6) at the end:

$$\begin{aligned}
E[g(Z)] &= E[E[g(Z) | I]] = qh(1) + (1 - q)h(0) = E[h(I)] \\
&= qE[g(Z) | I = 1] + (1 - q)E[g(Z) | I = 0] \\
&= qE[g(X) | I = 1] + (1 - q)E[g(Y) | I = 0] \\
&= qE[g(X)] + (1 - q)E[g(Y)] \\
&= q \sum_z g(z) \Pr[X = z] + (1 - q) \int_{-\infty}^{\infty} g(z) \frac{d}{dz} \Pr[Y \leq z] dz \\
&= \sum_z g(z) [F(z) - F(z - 0)] + \int_{-\infty}^{\infty} g(z) F'(z) dz.
\end{aligned} \tag{2.8}$$

Remark 2.2.1 (Riemann-Stieltjes integrals)

The result in (2.8), consisting of a sum and an ordinary Riemann integral, can be written as a right hand Riemann-Stieltjes integral:

$$E[g(Z)] = \int_{-\infty}^{\infty} g(z) dF(z). \tag{2.9}$$

The integrator is the differential $dF(z) = F_Z(z) - F_Z(z - dz)$. It replaces the probability of z , that is, the height of the step at z if there is one, or $F'(z) dz$ if there is no step at z . Here, dz denotes a positive infinitesimally small number. Note that the cdf $F(z) = \Pr[Z \leq z]$ is continuous from the right. In life insurance mathematics theory, Riemann-Stieltjes integrals were used as a tool to describe situations in which it is

vital which value of the integrand should be taken: the limit from the right, the limit from the left, or the actual function value. Actuarial practitioners have not adopted this convention. We avoid this problem altogether by considering continuous integrands only. ∇

Remark 2.2.2 (Mixed random variables and mixed distributions)

We can summarize the above as follows: a mixed continuous/discrete cdf $F_Z(z) = \Pr[Z \leq z]$ arises when a mixture of random variables

$$Z = IX + (1 - I)Y \quad (2.10)$$

is used, where X is a discrete random variable, Y is a continuous random variable and I is a Bernoulli(q) random variable, with X , Y and I independent. The cdf of Z is again a mixture, that is, a convex combination, of the cdfs of X and Y , see (2.5):

$$F_Z(z) = qF_X(z) + (1 - q)F_Y(z) \quad (2.11)$$

For expectations of functions $g(\cdot)$ of Z we get the same mixture of expectations of $E[g(X)]$ and $E[g(Y)]$, see (2.8):

$$E[g(Z)] = qE[g(X)] + (1 - q)E[g(Y)]. \quad (2.12)$$

It is important to make a distinction between the urn-of-urns model (2.10) leading to a convex combination of *cdfs*, and a convex combination of *random variables* $T = qX + (1 - q)Y$. Although (2.12) is valid for $T = Z$ in case $g(z) = z$, the random variable T does not have (2.11) as its cdf. See also Exercises 2.2.8 and 2.2.9. ∇

Example 2.2.3 (Insurance against bicycle theft)

We consider an insurance policy against bicycle theft that pays b in case the bicycle is stolen, upon which event the policy ends. Obviously, the number of payments is 0 or 1 and the amount is known in advance, just as with life insurance policies. Assume that the probability of theft is q and let $X = Ib$ denote the claim payment, where I is a Bernoulli(q) distributed indicator random variable, with $I = 1$ if the bicycle is stolen, $I = 0$ if not. In analogy to (2.4), we can rewrite X as $X = Ib + (1 - I)0$. The distribution and the moments of X can be obtained from those of I :

$$\begin{aligned} \Pr[X = b] &= \Pr[I = 1] = q; & \Pr[X = 0] &= \Pr[I = 0] = 1 - q; \\ E[X] &= bE[I] = bq; & \text{Var}[X] &= b^2\text{Var}[I] = b^2q(1 - q). \end{aligned} \quad (2.13)$$

Now suppose that only half the amount is paid out in case the bicycle was not locked. Some bicycle theft insurance policies have a restriction like this. Insurers check this by requiring that all the original keys have to be handed over in the event of a claim. Then, $X = IB$, where B represents the random payment. Assuming that the probabilities of a claim $X = 400$ and $X = 200$ are 0.05 and 0.15, we get

$$\Pr[I = 1, B = 400] = 0.05; \quad \Pr[I = 1, B = 200] = 0.15. \quad (2.14)$$

Hence, $\Pr[I = 1] = 0.2$ and consequently $\Pr[I = 0] = 0.8$. Also,

$$\Pr[B = 400 | I = 1] = \frac{\Pr[B = 400, I = 1]}{\Pr[I = 1]} = 0.25. \quad (2.15)$$

This represents the conditional probability that the bicycle was locked given the fact that it was stolen. ∇

Example 2.2.4 (Exponential claim size, if there is a claim)

Suppose that risk X is distributed as follows:

1. $\Pr[X = 0] = \frac{1}{2}$;
2. $\Pr[X \in [x, x + dx)] = \frac{1}{2}\beta e^{-\beta x} dx$ for $\beta = 0.1, x > 0$,

where dx denotes a positive infinitesimal number. What is the expected value of X , and what is the maximum premium for X that someone with an exponential utility function with risk aversion $\alpha = 0.01$ is willing to pay?

The random variable X is not continuous, because the cdf of X has a step in 0. It is also not a discrete random variable, since the cdf is not a step function; its derivative, which in terms of infinitesimal numbers equals $\Pr[x \leq X < x + dx]/dx$, is positive for $x > 0$. We can calculate the expectations of functions of X by dealing with the steps in the cdf separately, see (2.9). This leads to

$$E[X] = \int_{-\infty}^{\infty} x dF_X(x) = 0 dF_X(0) + \int_0^{\infty} x F_X'(x) dx = \frac{1}{2} \int_0^{\infty} x \beta e^{-\beta x} dx = 5. \quad (2.16)$$

If the utility function of the insured is exponential with parameter $\alpha = 0.01$, then (1.21) yields for the maximum premium P^+ :

$$\begin{aligned} P^+ &= \frac{1}{\alpha} \log(m_X(\alpha)) = \frac{1}{\alpha} \log \left(e^0 dF_X(0) + \frac{1}{2} \int_0^{\infty} e^{\alpha x} \beta e^{-\beta x} dx \right) \\ &= \frac{1}{\alpha} \log \left(\frac{1}{2} + \frac{1}{2} \frac{\beta}{\beta - \alpha} \right) = 100 \log \left(\frac{19}{18} \right) \approx 5.4. \end{aligned} \quad (2.17)$$

This same result can of course be obtained by writing X as in (2.10). ∇

Example 2.2.5 (Liability insurance with a maximum coverage)

Consider an insurance policy against a liability loss S . We want to determine the expected value, the variance and the distribution function of the payment X on this policy, when there is a deductible of 100 and a maximum payment of 1000. In other words, if $S \leq 100$ then $X = 0$, if $S \geq 1100$ then $X = 1000$, otherwise $X = S - 100$. The probability of a positive claim ($S > 100$) is 10% and the probability of a large loss ($S \geq 1100$) is 2%. Given $100 < S < 1100$, S has a uniform(100, 1100) distribution. Again, we write $X = IB$ where I denotes the number of payments, 0 or 1, and B represents the amount paid, if any. Therefore,

$$\begin{aligned} \Pr[B = 1000 | I = 1] &= 0.2; \\ \Pr[B \in (x, x + dx) | I = 1] &= c dx \quad \text{for } 0 < x < 1000. \end{aligned} \quad (2.18)$$

Integrating the latter probability over $x \in (0, 1000)$ yields 0.8, so $c = 0.0008$.

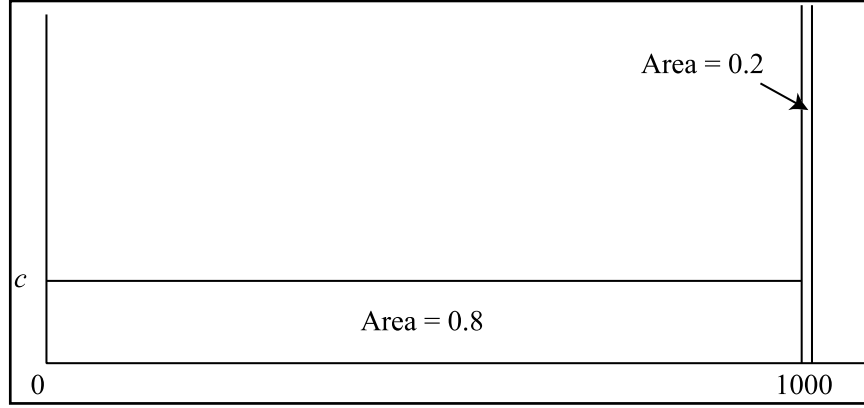


Fig. 2.1 ‘Probability density function’ of B given $I = 1$ in Example 2.2.5.

The conditional distribution function of B , given $I = 1$, is neither discrete, nor continuous. In Figure 2.1 we attempt to depict a pdf by representing the probability mass at 1000 by a bar of infinitesimal width and infinite height such that the area equals 0.2. In actual fact we have plotted $f(\cdot)$, where $f(x) = 0.0008$ on $(0, 1000)$ and $f(x) = 0.2/\varepsilon$ on $(1000, 1000 + \varepsilon)$ with $\varepsilon > 0$ very small.

For the cdf F of X we have

$$\begin{aligned} F(x) &= \Pr[X \leq x] = \Pr[IB \leq x] \\ &= \Pr[IB \leq x, I = 0] + \Pr[IB \leq x, I = 1] \\ &= \Pr[IB \leq x | I = 0] \Pr[I = 0] + \Pr[IB \leq x | I = 1] \Pr[I = 1] \end{aligned} \quad (2.19)$$

which yields

$$F(x) = \begin{cases} 0 \times 0.9 + 0 \times 0.1 = 0 & \text{for } x < 0 \\ 1 \times 0.9 + 1 \times 0.1 = 1 & \text{for } x \geq 1000 \\ 1 \times 0.9 + c \cdot x \times 0.1 & \text{for } 0 \leq x < 1000. \end{cases} \quad (2.20)$$

A graph of the cdf F is shown in Figure 2.2. For the differential (‘density’) of F , we have

$$dF(x) = \begin{cases} 0.9 & \text{for } x = 0 \\ 0.02 & \text{for } x = 1000 \\ 0 & \text{for } x < 0 \text{ or } x > 1000 \\ 0.00008 \, dx & \text{for } 0 < x < 1000. \end{cases} \quad (2.21)$$

The moments of X can be calculated by using this differential. ∇

The variance of risks of the form IB can be calculated through the conditional distribution of B , given I , by use of the well-known *variance decomposition rule*, see (2.7), which is also known as the law of total variance:

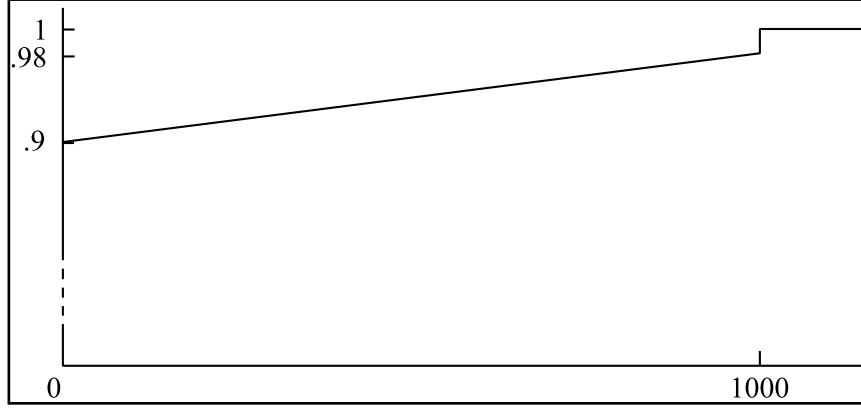


Fig. 2.2 Cumulative distribution function F of X in Example 2.2.5.

$$\text{Var}[W] = \text{Var}[E[W | V]] + E[\text{Var}[W | V]]. \quad (2.22)$$

In statistics, the first term is the component of the variance of W , not explained by knowledge of V ; the second is the explained component of the variance. The conditional distribution of $B | I = 0$ is irrelevant, so for convenience, we let it be equal to the one of $B | I = 1$, meaning that we take I and B to be independent. Then, letting $q = \Pr[I = 1]$, $\mu = E[B]$ and $\sigma^2 = \text{Var}[B]$, we have $E[X | I = 1] = \mu$ and $E[X | I = 0] = 0$. Therefore, $E[X | I = i] = \mu i$ for both values $i = 0, 1$, and analogously, $\text{Var}[X | I = i] = \sigma^2 i$. Hence,

$$E[X | I] \equiv \mu I \quad \text{and} \quad \text{Var}[X | I] \equiv \sigma^2 I, \quad (2.23)$$

from which it follows that

$$\begin{aligned} E[X] &= E[E[X | I]] = E[\mu I] = \mu q; \\ \text{Var}[X] &= \text{Var}[E[X | I]] + E[\text{Var}[X | I]] = \text{Var}[\mu I] + E[\sigma^2 I] \\ &= \mu^2 q(1 - q) + \sigma^2 q. \end{aligned} \quad (2.24)$$

Notice that a continuous cdf F is not necessarily absolutely continuous in the sense of (2.3), as is demonstrated by the following example.

Example 2.2.6 ([♠] The Cantor cdf; continuous but not absolutely continuous)

Let X_1, X_2, \dots be an infinite sequence of independent Bernoulli(1/2) random variables. Define the following random variable:

$$W = \sum_{i=1}^{\infty} \frac{2X_i}{3^i} = \frac{2}{3}X_1 + \frac{1}{3} \sum_{i=1}^{\infty} \frac{2X_{i+1}}{3^i} \quad (2.25)$$

Then the possible values of W are, in the ternary system, $0.d_1d_2d_3\dots$ with $d_i \in \{0, 2\}$ for all $i = 1, 2, \dots$, and with $d_i = 2$ occurring if $X_i = 1$. Obviously, all of these

values have zero probability as they correspond to *all* X_i having specific outcomes, so F_W is continuous.

Also, all intervals of real numbers in $(0, 1)$ having a ternary digit $d_i = 1$ on some place $i = 1, 2, \dots, n$ are not possible values of W , hence F_W is constant on the union B_n of all those intervals. But it is easy to see that the total length of these intervals tends to 1 as $n \rightarrow \infty$.

So we have constructed a continuous cdf F_W , known as the *Cantor distribution function*, that is constant except on a set of length 0 (known as the *Cantor set*). The cdf F_W cannot be equal to the integral over its derivative, since this is zero almost everywhere with respect to the Lebesgue measure ('interval length'). So though F_W is continuous, it is not absolutely continuous as in (2.3). ∇

2.3 Convolution

In the individual risk model we are interested in the distribution of the total S of the claims on a number of policies, with

$$S = X_1 + X_2 + \dots + X_n, \quad (2.26)$$

where X_i , $i = 1, 2, \dots, n$, denotes the payment on policy i . The risks X_i are assumed to be independent random variables. If this assumption is violated for some risks, for example in case of fire insurance policies on different floors of the same building, then these risks could be combined into one term in (2.26).

The operation 'convolution' calculates the distribution function of $X + Y$ from the cdfs of two independent random variables X and Y as follows:

$$\begin{aligned} F_{X+Y}(s) &= \Pr[X + Y \leq s] \\ &= \int_{-\infty}^{\infty} \Pr[X + Y \leq s | X = x] dF_X(x) \\ &= \int_{-\infty}^{\infty} \Pr[Y \leq s - x | X = x] dF_X(x) \\ &= \int_{-\infty}^{\infty} \Pr[Y \leq s - x] dF_X(x) \\ &= \int_{-\infty}^{\infty} F_Y(s - x) dF_X(x) =: F_X * F_Y(s). \end{aligned} \quad (2.27)$$

The cdf $F_X * F_Y(\cdot)$ is called the convolution of the cdfs $F_X(\cdot)$ and $F_Y(\cdot)$. For the density function we use the same notation. If X and Y are discrete random variables, we find for the cdf of $X + Y$ and the corresponding density

$$F_X * F_Y(s) = \sum_x F_Y(s - x) f_X(x) \quad \text{and} \quad f_X * f_Y(s) = \sum_x f_Y(s - x) f_X(x), \quad (2.28)$$

where the sum is taken over all x with $f_X(x) > 0$. If X and Y are continuous random variables, then

$$F_X * F_Y(s) = \int_{-\infty}^{\infty} F_Y(s-x)f_X(x) dx \quad (2.29)$$

and, taking the derivative under the integral sign to find the density,

$$f_X * f_Y(s) = \int_{-\infty}^{\infty} f_Y(s-x)f_X(x) dx. \quad (2.30)$$

Since $X + Y \equiv Y + X$, the convolution operator $*$ is *commutative*: $F_X * F_Y$ is identical to $F_Y * F_X$. Also, it is *associative*, since for the cdf of $X + Y + Z$, it does not matter in which order we do the convolutions, therefore

$$(F_X * F_Y) * F_Z \equiv F_X * (F_Y * F_Z) \equiv F_X * F_Y * F_Z. \quad (2.31)$$

For the sum of n independent and identically distributed random variables with marginal cdf F , the cdf is the n -fold convolution power of F , which we write as

$$F * F * \cdots * F =: F^{*n}. \quad (2.32)$$

Example 2.3.1 (Convolution of two uniform distributions)

Suppose that $X \sim \text{uniform}(0,1)$ and $Y \sim \text{uniform}(0,2)$ are independent. What is the cdf of $X + Y$?

The indicator function of a set A is defined as follows:

$$I_A(x) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{if } x \notin A. \end{cases} \quad (2.33)$$

Indicator functions provide us with a concise notation for functions that are defined differently on some intervals. For all x , the cdf of X can be written as

$$F_X(x) = xI_{[0,1)}(x) + I_{[1,\infty)}(x), \quad (2.34)$$

while $F_Y'(y) = \frac{1}{2}I_{[0,2)}(y)$ for all y , which leads to the differential

$$dF_Y(y) = \frac{1}{2}I_{[0,2)}(y) dy. \quad (2.35)$$

The convolution formula (2.27), applied to $Y + X$ rather than $X + Y$, then yields

$$F_{Y+X}(s) = \int_{-\infty}^{\infty} F_X(s-y) dF_Y(y) = \int_0^2 F_X(s-y) \frac{1}{2} dy, \quad s \geq 0. \quad (2.36)$$

The interval of interest is $0 \leq s < 3$. Subdividing it into $[0, 1)$, $[1, 2)$ and $[2, 3)$ yields

$$\begin{aligned}
F_{X+Y}(s) &= \left\{ \int_0^s (s-y) \frac{1}{2} dy \right\} I_{[0,1)}(s) \\
&\quad + \left\{ \int_0^{s-1} \frac{1}{2} dy + \int_{s-1}^s (s-y) \frac{1}{2} dy \right\} I_{[1,2)}(s) \\
&\quad + \left\{ \int_0^{s-1} \frac{1}{2} dy + \int_{s-1}^2 (s-y) \frac{1}{2} dy \right\} I_{[2,3)}(s) \\
&= \frac{1}{4} s^2 I_{[0,1)}(s) + \frac{1}{4} (2s-1) I_{[1,2)}(s) + \left[1 - \frac{1}{4} (3-s)^2 \right] I_{[2,3)}(s).
\end{aligned} \tag{2.37}$$

Notice that $X + Y$ is symmetric around $s = 1.5$. Although this problem could be solved graphically by calculating the probabilities by means of areas, see Exercise 2.3.5, the above derivation provides an excellent illustration that, even in simple cases, convolution can be a laborious process. ∇

Example 2.3.2 (Convolution of discrete distributions)

Let $f_1(x) = \frac{1}{4}, \frac{1}{2}, \frac{1}{4}$ for $x = 0, 1, 2$, $f_2(x) = \frac{1}{2}, \frac{1}{2}$ for $x = 0, 2$ and $f_3(x) = \frac{1}{4}, \frac{1}{2}, \frac{1}{4}$ for $x = 0, 2, 4$. Let f_{1+2} denote the convolution of f_1 and f_2 and let f_{1+2+3} denote the convolution of f_1 , f_2 and f_3 . To calculate F_{1+2+3} , we need to compute the values as shown in Table 2.1. In the discrete case, too, convolution is clearly a laborious exercise. Note that the more often we have $f_i(x) \neq 0$, the more calculations need to be done. ∇

Table 2.1 Convolution computations for Example 2.3.2

x	$f_1(x)$	$f_2(x)$	$f_{1+2}(x)$	$f_3(x)$	$f_{1+2+3}(x)$	$F_{1+2+3}(x)$
0	1/4	1/2	1/8	1/4	1/32	1/32
1	1/2	0	2/8	0	2/32	3/32
2	1/4	1/2	2/8	1/2	4/32	7/32
3	0	0	2/8	0	6/32	13/32
4	0	0	1/8	1/4	6/32	19/32
5	0	0	0	0	6/32	25/32
6	0	0	0	0	4/32	29/32
7	0	0	0	0	2/32	31/32
8	0	0	0	0	1/32	32/32

Example 2.3.3 (Convolution of iid uniform distributions)

Let X_i , $i = 1, 2, \dots, n$, be independent and identically uniform(0, 1) distributed. By using the convolution formula and induction, it can be shown that for all $x > 0$, the pdf of $S = X_1 + \dots + X_n$ equals

$$f_S(x) = \frac{1}{(n-1)!} \sum_{h=0}^{\lfloor x \rfloor} \binom{n}{h} (-1)^h (x-h)^{n-1} \tag{2.38}$$

where $\lfloor x \rfloor$ denotes the integer part of x . See also Exercise 2.3.4. ∇

Example 2.3.4 (Convolution of Poisson distributions)

Let $X \sim \text{Poisson}(\lambda)$ and $Y \sim \text{Poisson}(\mu)$ be independent random variables. From (2.28) we have, for $s = 0, 1, 2, \dots$,

$$\begin{aligned} f_{X+Y}(s) &= \sum_{x=0}^s f_Y(s-x)f_X(x) = \frac{e^{-\mu-\lambda}}{s!} \sum_{x=0}^s \binom{s}{x} \mu^{s-x} \lambda^x \\ &= e^{-(\lambda+\mu)} \frac{(\lambda+\mu)^s}{s!}, \end{aligned} \quad (2.39)$$

where the last equality is the binomial theorem. Hence, $X + Y$ is $\text{Poisson}(\lambda + \mu)$ distributed. For a different proof, see Exercise 2.4.2. ∇

2.4 Transforms

Determining the distribution of the sum of independent random variables can often be made easier by using transforms of the cdf. The *moment generating function* (mgf) suits our purposes best. For a non-negative random variable X , it is defined as

$$m_X(t) = E[e^{tX}], \quad -\infty < t < h, \quad (2.40)$$

for some h . The mgf is going to be used especially in an interval around 0, which requires $h > 0$ to hold. Note that this is the case only for light-tailed risks, of which exponential moments $E[e^{\varepsilon X}]$ for some $\varepsilon > 0$ exist.

If X and Y are independent, then

$$m_{X+Y}(t) = E[e^{t(X+Y)}] = E[e^{tX}] E[e^{tY}] = m_X(t) m_Y(t). \quad (2.41)$$

So, the convolution of cdfs corresponds to simply multiplying the mgfs. Note that the mgf-transform is one-to-one, so every cdf has exactly one mgf. Also, it is continuous, in the sense that the mgf of the limit of a series of cdfs is the limit of the mgfs. See Exercises 2.4.12 and 2.4.13.

For random variables with a heavy tail, such as the Pareto distributions, the mgf does not exist. The *characteristic function*, however, always exists. It is defined as:

$$\phi_X(t) = E[e^{itX}] = E[\cos(tX) + i\sin(tX)], \quad -\infty < t < \infty. \quad (2.42)$$

A disadvantage of the characteristic function is the need to work with complex numbers, although applying the same function formula derived for real t to imaginary t as well produces the correct results most of the time, resulting for example in the $N(0, 2)$ distribution with mgf $\exp(t^2)$ having $\exp((it)^2) = \exp(-t^2)$ as its characteristic function.

As their name indicates, moment generating functions can be used to generate moments of random variables. The usual series expansion of e^x yields

$$m_X(t) = E[e^{tX}] = \sum_{k=0}^{\infty} \frac{E[X^k] t^k}{k!}, \quad (2.43)$$

so the k -th moment of X equals

$$E[X^k] = \left. \frac{d^k}{dt^k} m_X(t) \right|_{t=0}. \quad (2.44)$$

Moments can also be generated from the characteristic function in similar fashion.

The *probability generating function* (pgf) is reserved for random variables with natural numbers as values:

$$g_X(t) = E[t^X] = \sum_{k=0}^{\infty} t^k \Pr[X = k]. \quad (2.45)$$

So, the probabilities $\Pr[X = k]$ in (2.45) are just the coefficients in the series expansion of the pgf. The series (2.45) converges absolutely if $|t| \leq 1$.

The *cumulant generating function* (cgf) is convenient for calculating the third central moment; it is defined as:

$$\kappa_X(t) = \log m_X(t). \quad (2.46)$$

Differentiating (2.46) three times and setting $t = 0$, one sees that the coefficients of $t^k/k!$ for $k = 1, 2, 3$ are $E[X]$, $\text{Var}[X]$ and $E[(X - E[X])^3]$. The quantities generated this way are the *cumulants* of X , and they are denoted by κ_k , $k = 1, 2, \dots$. One may also proceed as follows: let μ_k denote $E[X^k]$ and let, as usual, the ‘big O notation’ $O(t^k)$ denote ‘terms of order t to the power k or higher’. Then

$$m_X(t) = 1 + \mu_1 t + \frac{1}{2} \mu_2 t^2 + \frac{1}{6} \mu_3 t^3 + O(t^4), \quad (2.47)$$

which, using $\log(1+z) = z - \frac{1}{2}z^2 + \frac{1}{3}z^3 + O(z^4)$, yields

$$\begin{aligned} \log m_X(t) &= \log \left(1 + \mu_1 t + \frac{1}{2} \mu_2 t^2 + \frac{1}{6} \mu_3 t^3 + O(t^4) \right) \\ &= \mu_1 t + \frac{1}{2} \mu_2 t^2 + \frac{1}{6} \mu_3 t^3 + O(t^4) \\ &\quad - \frac{1}{2} \{ \mu_1^2 t^2 + \mu_1 \mu_2 t^3 + O(t^4) \} \\ &\quad + \frac{1}{3} \{ \mu_1^3 t^3 + O(t^4) \} + O(t^4) \\ &= \mu_1 t + \frac{1}{2} (\mu_2 - \mu_1^2) t^2 + \frac{1}{6} (\mu_3 - 3\mu_1 \mu_2 + 2\mu_1^3) t^3 + O(t^4) \\ &= E[X]t + \text{Var}[X] \frac{1}{2} t^2 + E[(X - E[X])^3] \frac{1}{6} t^3 + O(t^4). \end{aligned} \quad (2.48)$$

The *skewness* of a random variable X is defined as the following dimension-free quantity:

$$\gamma_X = \frac{\kappa_3}{\sigma^3} = \frac{E[(X - \mu)^3]}{\sigma^3}, \quad (2.49)$$

with $\mu = E[X]$ and $\sigma^2 = \text{Var}[X]$. If $\gamma_X > 0$, large values of $X - \mu$ are likely to occur, hence the (right) tail of the cdf is heavy. A negative skewness $\gamma_X < 0$ indicates a heavy left tail. If X is symmetric then $\gamma_X = 0$, but having zero skewness is not sufficient for symmetry. For some counterexamples, see the exercises.

The cumulant generating function, the probability generating function, the characteristic function and the moment generating function are related by

$$\kappa_X(t) = \log m_X(t); \quad g_X(t) = m_X(\log t); \quad \phi_X(t) = m_X(it). \quad (2.50)$$

In Exercise 2.4.14 the reader is asked to examine the last of these equalities. Often the mgf can be extended to the whole complex plane in a natural way. The mgf operates on the real axis, the characteristic function on the imaginary axis.

2.5 Approximations

A well-known method to approximate a cdf is based on the Central Limit Theorem (CLT). We study this approximation as well as two more accurate ones that involve three moments rather than just two.

2.5.1 Normal approximation

Next to the Law of Large Numbers, the Central Limit Theorem is the most important theorem in statistics. It states that by adding up a large number of independent random variables, we get a normally distributed random variable in the limit. In its simplest form, the Central Limit Theorem (CLT) is as follows:

Theorem 2.5.1 (Central Limit Theorem)

If X_1, X_2, \dots, X_n are independent and identically distributed random variables with mean μ and variance $\sigma^2 < \infty$, then

$$\lim_{n \rightarrow \infty} \Pr \left[\sum_{i=1}^n X_i \leq n\mu + x\sigma\sqrt{n} \right] = \Phi(x). \quad (2.51)$$

Proof. We restrict ourselves to proving the convergence of the sequence of cgfs. Let $S^* = (X_1 + \dots + X_n - n\mu)/\sigma\sqrt{n}$, then for $n \rightarrow \infty$ and for all t :

$$\begin{aligned} \log m_{S^*}(t) &= -\frac{\sqrt{n}\mu t}{\sigma} + n \left\{ \log m_X\left(\frac{t}{\sigma\sqrt{n}}\right) \right\} \\ &= -\frac{\sqrt{n}\mu t}{\sigma} + n \left\{ \mu \left(\frac{t}{\sigma\sqrt{n}}\right) + \frac{1}{2}\sigma^2 \left(\frac{t}{\sigma\sqrt{n}}\right)^2 + O\left(\left(\frac{1}{\sqrt{n}}\right)^3\right) \right\} \\ &= \frac{1}{2}t^2 + O\left(\frac{1}{\sqrt{n}}\right), \end{aligned} \quad (2.52)$$

which converges to the cgf of the $N(0, 1)$ distribution, with mgf $\exp(\frac{1}{2}t^2)$. As a consequence, the cdf of S^* converges to the standard normal cdf Φ . ∇

As a result, if the summands are *independent* and have *finite* variance, we can approximate the cdf of $S = X_1 + \cdots + X_n$ by

$$F_S(s) \approx \Phi \left(s; \sum_{i=1}^n E[X_i], \sum_{i=1}^n \text{Var}[X_i] \right). \quad (2.53)$$

This approximation can safely be used if n is ‘large’. But it is difficult to define ‘large’, as is shown in the following examples.

Example 2.5.2 (Generating approximately normal random deviates fast)

If pseudo-random numbers can be generated fast (using bit-manipulations), but computing logarithms and the inverse normal cdf takes a lot of time, approximately $N(0, 1)$ distributed pseudo-random drawings numbers can conveniently be produced by adding up twelve uniform(0, 1) numbers and subtracting 6 from their sum. This technique is based on the CLT with $n = 12$. Comparing this cdf with the normal cdf, using (2.38), yields a maximum difference of 0.002. Hence, the CLT performs quite well in this case. See also Exercise 2.4.5. ∇

Example 2.5.3 (Illustrating the various approximations)

Suppose that $n = 1000$ young men take out a life insurance policy for a period of one year. The probability of dying within this year is 0.001 for everyone and the payment for every death is 1. We want to calculate the probability that the total payment is at least 4. This total payment is binomial(1000, 0.001) distributed and since $n = 1000$ is large and $p = 0.001$ is small, we will approximate this probability by a Poisson(np) distribution. Calculating the probability at $3 + \frac{1}{2}$ instead of at 4, applying a continuity correction needed later on, we find

$$\Pr[S \geq 3.5] = 1 - e^{-1} - e^{-1} - \frac{1}{2}e^{-1} - \frac{1}{6}e^{-1} = 0.01899. \quad (2.54)$$

Note that the exact binomial probability is 0.01893. Although n is much larger than in the previous example, the CLT gives a poor approximation: with $\mu = E[S] = 1$ and $\sigma^2 = \text{Var}[S] = 1$, we find

$$\Pr[S \geq 3.5] = \Pr \left[\frac{S - \mu}{\sigma} \geq \frac{3.5 - \mu}{\sigma} \right] \approx 1 - \Phi(2.5) = 0.0062. \quad (2.55)$$

The CLT approximation is not very good because of the extreme skewness of the terms X_i and the resulting skewness of S , which is $\gamma_S = 1$. In the previous example, we started from symmetric terms, leading to a higher order of convergence, as can be seen from derivation (2.52). ∇

As an alternative for the CLT, we give two more refined approximations: the translated gamma approximation and the normal power approximation (NP). In numerical examples, they turn out to be much more accurate than the CLT approximation. As regards the quality of the approximations, there is not much to choose between

the two. Their inaccuracies are minor compared with the errors that result from the lack of precision in the estimates of the first three moments that are involved.

2.5.2 Translated gamma approximation

Most total claim distributions are skewed to the right (skewness $\gamma > 0$), have a non-negative support and are unimodal. So they have roughly the shape of a gamma distribution. To gain more flexibility, apart from the usual parameters α and β we allow a shift over a distance x_0 . Hence, we approximate the cdf of S by the cdf of $Z + x_0$, where $Z \sim \text{gamma}(\alpha, \beta)$ (see Table A). We choose α , β and x_0 in such a way that the approximating random variable has the same first three moments as S .

The translated gamma approximation can then be formulated as follows:

$$F_S(s) \approx G(s - x_0; \alpha, \beta),$$

$$\text{where } G(x; \alpha, \beta) = \frac{1}{\Gamma(\alpha)} \int_0^x y^{\alpha-1} \beta^\alpha e^{-\beta y} dy, \quad x \geq 0. \quad (2.56)$$

Here $G(x; \alpha, \beta)$ is the gamma cdf. We choose α , β and x_0 such that the first three moments are the same, hence $\mu = x_0 + \frac{\alpha}{\beta}$, $\sigma^2 = \frac{\alpha}{\beta^2}$ and $\gamma = \frac{2}{\sqrt{\alpha}}$ (see Table A), so

$$\alpha = \frac{4}{\gamma^2}, \quad \beta = \frac{2}{\gamma\sigma} \quad \text{and} \quad x_0 = \mu - \frac{2\sigma}{\gamma}. \quad (2.57)$$

It is required that the skewness γ is strictly positive. In the limit $\gamma \downarrow 0$, the normal approximation appears. Note that if the first three moments of the cdf $F(\cdot)$ are equal to those of $G(\cdot)$, by partial integration it can be shown that the same holds for $\int_0^\infty x^j [1 - F(x)] dx$, $j = 0, 1, 2$. This leaves little room for these cdfs to be very different from each other.

Example 2.5.4 (Illustrating the various approximations, continued)

If $S \sim \text{Poisson}(1)$, we have $\mu = \sigma = \gamma = 1$, and (2.57) yields $\alpha = 4$, $\beta = 2$ and $x_0 = -1$. Hence, $\Pr[S \geq 3.5] \approx 1 - G(3.5 - (-1); 4, 2) = 0.0212$. This value is much closer to the exact value than the CLT approximation. ∇

The translated gamma approximation leads to quite simple formulas to approximate the moments of a stop-loss claim $(S - d)_+$ or of the retained loss $S - (S - d)_+$. To evaluate the gamma cdf is easy in R, and in spreadsheet programs the gamma distribution is also included, although the accuracy sometimes leaves much to be desired. Note that in many applications, for example MS Excel, the parameter β should be replaced by $1/\beta$. In R, specify $\beta = 2$ by using `rate=2`, or by `scale=1/2`.

Example 2.5.5 (Translated gamma approximation)

A total claim amount S has expected value 10000, standard deviation 1000 and skewness 1. From (2.57) we have $\alpha = 4$, $\beta = 0.002$ and $x_0 = 8000$. Hence,

$$\Pr[S > 13000] \approx 1 - G(13000 - 8000; 4, 0.002) = 0.010. \quad (2.58)$$

The regular CLT approximation is much smaller: 0.0013. Using the inverse of the gamma distribution function, the value-at-risk on a 95% level is found by reversing the computation (2.58), resulting in 11875. ∇

2.5.3 NP approximation

Another approximation that uses three moments of the approximated random variable is the Normal Power approximation. It goes as follows.

If $E[S] = \mu$, $\text{Var}[S] = \sigma^2$ and $\gamma_S = \gamma$, then, for $s \geq 1$,

$$\Pr\left[\frac{S - \mu}{\sigma} \leq s + \frac{\gamma}{6}(s^2 - 1)\right] \approx \Phi(s) \quad (2.59)$$

or, equivalently, for $x \geq 1$,

$$\Pr\left[\frac{S - \mu}{\sigma} \leq x\right] \approx \Phi\left(\sqrt{\frac{9}{\gamma^2} + \frac{6x}{\gamma} + 1} - \frac{3}{\gamma}\right). \quad (2.60)$$

The second formula can be used to approximate the cdf of S , the first produces approximate quantiles. If $s < 1$ (or $x < 1$), the correction term is negative, which implies that the CLT gives more conservative results.

Example 2.5.6 (Illustrating the various approximations, continued)

If $S \sim \text{Poisson}(1)$, then the NP approximation yields $\Pr[S \geq 3.5] \approx 1 - \Phi(2) = 0.0228$. Again, this is a better result than the CLT approximation.

The R-calls needed to produce all the numerical values are the following:

```
x <- 3.5; mu <- 1; sig <- 1; gam <- 1; z <- (x-mu)/sig
1-pbinom(x, 1000, 0.001)          ## 0.01892683
1-ppois(x, 1)                     ## 0.01898816
1-pnorm(z)                        ## 0.00620967
1-pnorm(sqrt(9/gam^2 + 6*z/gam + 1) - 3/gam) ## 0.02275013
1-pgamma(x-(mu-2*sig/gam), 4/gam^2, 2/gam/sig) ## 0.02122649
```

Equations (2.53), (2.60) and (2.56)–(2.57) were used. ∇

Example 2.5.7 (Recalculating Example 2.5.5 by the NP approximation)

We apply (2.59) to determine the capital that covers loss S with probability 95%:

$$\Pr\left[\frac{S - \mu}{\sigma} \leq s + \frac{\gamma}{6}(s^2 - 1)\right] \approx \Phi(s) = 0.95 \quad \text{if } s = 1.645, \quad (2.61)$$

hence for the desired 95% quantile of S we find

$$E[S] + \sigma_S \left(1.645 + \frac{\gamma}{6}(1.645^2 - 1)\right) = E[S] + 1.929\sigma_S = 11929. \quad (2.62)$$

To determine the probability that capital 13000 will be insufficient to cover the losses S , we apply (2.60) with $\mu = 10000$, $\sigma = 1000$ and $\gamma = 1$:

$$\begin{aligned}\Pr[S > 13000] &= \Pr\left[\frac{S - \mu}{\sigma} > 3\right] \approx 1 - \Phi(\sqrt{9 + 6 \times 3 + 1} - 3) \\ &= 1 - \Phi(2.29) = 0.011.\end{aligned}\quad (2.63)$$

Note that the translated gamma approximation gave 0.010, against only 0.0013 for the CLT. ∇

Remark 2.5.8 (Justifying the NP approximation)

For $U \sim N(0, 1)$, consider the random variable $Y = U + \frac{\gamma}{6}(U^2 - 1)$. It is easy to verify that (see Exercise 2.5.21), writing $w(x) = \sqrt{\left(\frac{9}{\gamma^2} + \frac{6x}{\gamma} + 1\right)_+}$, we have

$$F_Y(x) = \Phi\left(+w(x) - \frac{3}{\gamma}\right) - \Phi\left(-w(x) - \frac{3}{\gamma}\right) \approx \Phi\left(w(x) - \frac{3}{\gamma}\right). \quad (2.64)$$

The term $\Phi(-w(x) - 3/\gamma)$ accounts for small U leading to large Y . It is generally negligible, and vanishes as $\gamma \downarrow 0$.

Also, using $E[U^6] = 15$, $E[U^4] = 3$ and $E[U^2] = 1$, for small γ one can prove

$$E[Y] = 0; \quad E[Y^2] = 1 + O(\gamma^2); \quad E[Y^3] = \gamma(1 + O(\gamma^2)). \quad (2.65)$$

Therefore, the first three moments of $\frac{S - \mu}{\sigma}$ and Y as defined above are alike. This, with (2.64), justifies the use of formula (2.60) to approximate the cdf of $\frac{S - \mu}{\sigma}$. ∇

Remark 2.5.9 ([♠] Deriving NP using the Edgeworth expansion)

Formula (2.59) can be derived by the use of a certain expansion for the cdf, though not in a mathematically rigorous way. Define $Z = (S - E[S])/\sqrt{\text{Var}[S]}$, and let $\gamma = E[Z^3]$ be the skewness of S (and Z). For the cgf of Z we have

$$\log m_Z(t) = \frac{1}{2}t^2 + \frac{1}{6}\gamma t^3 + \dots, \quad (2.66)$$

hence

$$m_Z(t) = e^{t^2/2} \cdot \exp\left\{\frac{1}{6}\gamma t^3 + \dots\right\} = e^{t^2/2} \cdot \left(1 + \frac{1}{6}\gamma t^3 + \dots\right). \quad (2.67)$$

The ‘mgf’ (generalized to functions that are not a density) of $\varphi^{(3)}(x)$, with $\varphi(x)$ the $N(0, 1)$ density, can be found by partial integration:

$$\begin{aligned}\int_{-\infty}^{\infty} e^{tx} \varphi^{(3)}(x) dx &= e^{tx} \varphi^{(2)}(x) \Big|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} t e^{tx} \varphi^{(2)}(x) dx \\ &= 0 - 0 + \int_{-\infty}^{\infty} t^2 e^{tx} \varphi^{(1)}(x) dx \\ &= 0 - 0 + 0 - \int_{-\infty}^{\infty} t^3 e^{tx} \varphi(x) dx = -t^3 e^{t^2/2}.\end{aligned}\quad (2.68)$$

Therefore we recognize the cdf corresponding to mgf (2.67) as:

$$F_Z(x) = \Phi(x) - \frac{1}{6}\gamma\Phi^{(3)}(x) + \dots \quad (2.69)$$

Formula (2.69) is called the *Edgeworth expansion* for F_Z ; leaving out the dots gives an *Edgeworth approximation* for it. There is no guarantee that the latter is an increasing function. To derive the NP approximation formula (2.59) from it, we try to find a correction $\delta = \delta(s)$ to the argument s such that

$$F_Z(s + \delta) \approx \Phi(s). \quad (2.70)$$

That means that we have to find a zero for the auxiliary function $g(\delta)$ defined by

$$g(\delta) = \Phi(s) - \{\Phi(s + \delta) - \frac{1}{6}\gamma\Phi^{(3)}(s + \delta)\}. \quad (2.71)$$

Using a Taylor expansion $g(\delta) \approx g(0) + \delta g'(0)$ we may conclude that $g(\delta) = 0$ for $\delta \approx -g(0)/g'(0)$, so

$$\delta \approx \frac{-\frac{1}{6}\gamma\Phi^{(3)}(s)}{-\Phi'(s) + \frac{1}{6}\gamma\Phi^{(4)}(s)} = \frac{-\frac{1}{6}\gamma(s^2 - 1)\varphi(s)}{(-1 + \frac{1}{6}\gamma(-s^3 + 3s))\varphi(s)}. \quad (2.72)$$

Since the skewness γ is of order $\lambda^{-1/2}$, see for example (2.48), therefore small for large portfolios, we drop the term with γ in the denominator of (2.72), leading to

$$F_Z(s + \delta) \approx \Phi(s) \quad \text{when} \quad \delta = \frac{1}{6}\gamma(s^2 - 1). \quad (2.73)$$

This is precisely the NP approximation (2.59) given earlier.

The dots in formula (2.69) denote the inverse mgf-transform of the dots in (2.67). It is not possible to show that the terms replaced by dots in this formula are small, let alone their absolute sum. So it is an exaggeration to say that the approximations obtained this way, dropping terms of a possibly divergent series and then using an approximate inversion, are justified by theoretical arguments. ∇

2.6 Application: optimal reinsurance

An insurer is looking for an optimal reinsurance for a portfolio consisting of 20000 one-year life insurance policies that are grouped as follows:

Insured amount b_k	Number of policies n_k
1	10 000
2	5 000
3	5 000

The probability of dying within one year is $q_k = 0.01$ for each insured, and the policies are independent. The insurer wants to optimize the probability of being able to meet his financial obligations by choosing the best retention, which is the maximum payment per policy. The remaining part of a claim is paid by the reinsurer. For example, if the retention is 1.6 and someone with insured amount 2 dies, then the insurer pays 1.6, the reinsurer pays 0.4. After collecting the premiums, the insurer holds a capital B from which he has to pay the claims and the reinsurance premium. This premium is assumed to be 120% of the net premium.

First, we set the retention equal to 2. From the point of view of the insurer, the policies are then distributed as follows:

Insured amount b_k	Number of policies n_k
1	10 000
2	10 000

The expected value and the variance of the insurer's total claim amount S are equal to

$$\begin{aligned}
 E[S] &= n_1 b_1 q_1 + n_2 b_2 q_2 \\
 &= 10000 \times 1 \times 0.01 + 10000 \times 2 \times 0.01 = 300, \\
 \text{Var}[S] &= n_1 b_1^2 q_1 (1 - q_1) + n_2 b_2^2 q_2 (1 - q_2) \\
 &= 10000 \times 1 \times 0.01 \times 0.99 + 10000 \times 4 \times 0.01 \times 0.99 = 495.
 \end{aligned} \tag{2.74}$$

By applying the CLT, we get for the probability that the costs S plus the reinsurance premium $1.2 \times 0.01 \times 5000 \times 1 = 60$ exceed the available capital B :

$$\Pr[S + 60 > B] = \Pr\left[\frac{S - E[S]}{\sigma_S} > \frac{B - 360}{\sqrt{495}}\right] \approx 1 - \Phi\left(\frac{B - 360}{\sqrt{495}}\right). \tag{2.75}$$

We leave it to the reader to determine this same probability for retentions between 2 and 3, as well as to determine which retention for a given B leads to the largest probability of survival. See the exercises with this section.

2.7 Exercises

Section 2.2

1. Determine the expected value and the variance of $X = IB$ if the claim probability equals 0.1. First, assume that B equals 5 with probability 1. Then, let $B \sim \text{uniform}(0, 10)$.
2. Throw a true die and let X denote the outcome. Then, toss a coin X times. Let Y denote the number of heads obtained. What are the expected value and the variance of Y ?

3. In Example 2.2.4, plot the cdf of X . Also determine, with the help of the obtained differential, the premium the insured is willing to pay for being insured against an inflated loss $1.1X$. Do the same by writing $X = IB$. Has the zero utility premium followed inflation exactly?
4. Calculate $E[X]$, $\text{Var}[X]$ and the moment generating function $m_X(t)$ in Example 2.2.5 with the help of the differential. Also plot the ‘density’.
5. If $X = IB$, what is $m_X(t)$?
6. Consider the following cdf F : $F(x) = \begin{cases} 0 & \text{for } x < 2, \\ \frac{x}{4} & \text{for } 2 \leq x < 4, \\ 1 & \text{for } 4 \leq x. \end{cases}$
Determine independent random variables I , X and Y such that $Z = IX + (1 - I)Y$ has cdf F , $I \sim \text{Bernoulli}$, X is a discrete and Y a continuous random variable.
7. The differential of cdf F is $dF(x) = \begin{cases} dx/3 & \text{for } 0 < x < 1 \text{ and } 2 < x < 3, \\ \frac{1}{6} & \text{for } x \in \{1, 2\}, \\ 0 & \text{elsewhere.} \end{cases}$
Find a discrete cdf G , a continuous cdf H and a real constant c with the property that $F(x) = cG(x) + (1 - c)H(x)$ for all x .
8. Suppose that $T = qX + (1 - q)Y$ and $Z = IX + (1 - I)Y$ with $I \sim \text{Bernoulli}(q)$ and I , X and Y independent. Compare $E[T^k]$ with $E[Z^k]$, $k = 1, 2$.
9. In the previous exercise, assume additionally that X and Y are independent $N(0, 1)$. What distributions do T and Z have?
10. [♠] In Example 2.2.6, show that $E[W] = \frac{1}{2}$ and $\text{Var}[W] = \frac{1}{8}$.
Also show that $m_W(t) = e^{t/2} \prod_{i=1}^{\infty} \cosh(t/3^i)$. Recall that $\cosh(t) = (e^t + e^{-t})/2$.

Section 2.3

1. Calculate $\Pr[S = s]$ for $s = 0, 1, \dots, 6$ when $S = X_1 + 2X_2 + 3X_3$ and $X_j \sim \text{Poisson}(j)$.
2. Determine the number of multiplications of non-zero numbers that are needed for the calculation of all probabilities $f_{1+2+3}(x)$ in Example 2.3.2. How many multiplications are needed to calculate $F_{1+\dots+n}(x)$, $x = 0, \dots, 4n - 4$ if $f_k = f_3$ for $k = 4, \dots, n$?
3. Prove by convolution that the sum of two independent normal random variables, see Table A, has a normal distribution.
4. [♠] Verify the expression (2.38) in Example 2.3.3 for $n = 1, 2, 3$ by using convolution. Determine $F_S(x)$ for these values of n . Using induction, verify (2.38) for arbitrary n .
5. Assume that $X \sim \text{uniform}(0, 3)$ and $Y \sim \text{uniform}(-1, 1)$. Calculate $F_{X+Y}(z)$ graphically by using the area of the sets $\{(x, y) \mid x + y \leq z, x \in (0, 3) \text{ and } y \in (-1, 1)\}$.

Section 2.4

1. Determine the cdf of $S = X_1 + X_2$ where the X_k are independent and $\text{exponential}(k)$ distributed. Do this both by convolution and by calculating the mgf, identifying the corresponding density using the method of partial fractions.
2. Same as Example 2.3.4, but now by making use of the mgfs.
3. What is the fourth cumulant κ_4 in terms of the central moments?

4. Prove that cumulants actually cumulate in the following sense: if X and Y are independent, then the k th cumulant of $X + Y$ equals the sum of the k th cumulants of X and Y .
5. Prove that the sum of twelve independent uniform(0,1) random variables has variance 1 and expected value 6. Determine κ_3 and κ_4 .
Plot the difference between the cdf of this random variable and the $N(6, 1)$ cdf, using the expression for $F_S(x)$ found in Exercise 2.3.4.
6. Determine the skewness of a Poisson(μ) distribution.
7. Determine the skewness of a gamma(α, β) distribution.
8. If S is symmetric, then $\gamma_S = 0$. Prove this, but also, for $S = X_1 + X_2 + X_3$ with $X_1 \sim \text{Bernoulli}(0.4)$, $X_2 \sim \text{Bernoulli}(0.7)$ and $X_3 \sim \text{Bernoulli}(p)$, all independent, find a value of p such that S has skewness $\gamma_S = 0$, and verify that S is not symmetric.
9. Determine the skewness of a risk of the form Ib where $I \sim \text{Bernoulli}(q)$ and b is a fixed amount. For which values of q and b is the skewness equal to zero, and for which of these values is I actually symmetric?
10. Determine the pgf of the binomial, the Poisson and the negative binomial distribution, see Table A.
11. Determine the cgf and the cumulants of the following distributions: Poisson, binomial, normal and gamma.
12. Show that X and Y are equal in distribution if they have the same support $\{0, 1, \dots, n\}$ and the same pgf. If X_1, X_2, \dots are risks, again with range $\{0, 1, \dots, n\}$, such that the pgfs of X_i converge to the pgf of Y for each argument t when $i \rightarrow \infty$, verify that also $\Pr[X_i = x] \rightarrow \Pr[Y = x]$ for all x .
13. Show that X and Y are equal in distribution if they have the same support $\{0, \delta, 2\delta, \dots, n\delta\}$ for some $\delta > 0$ and moreover, they have the same mgf.
14. [♠] Examine the equality $\phi_X(t) = m_X(it)$ from (2.50), for the special case that $X \sim \text{exponential}(1)$. Show that the characteristic function is real-valued if X is symmetric around 0.
15. Show that the skewness of $Z = X + 2Y$ is 0 if $X \sim \text{binomial}(8, p)$ and $Y \sim \text{Bernoulli}(1 - p)$. For which values of p is Z symmetric?
16. For which values of δ is the skewness of $X - \delta Y$ equal to 0, if $X \sim \text{gamma}(2, 1)$ and $Y \sim \text{exponential}(1)$?
17. Can the pgf of a random variable be used to generate moments? Can the mgf of an integer-valued random variable be used to generate probabilities?

Section 2.5

1. What happens if we replace the argument 3.5 in Example 2.5.3 by $3 - 0$, $3 + 0$, $4 - 0$ and $4 + 0$? Is a correction for continuity needed here?
2. Prove that both versions of the NP approximation are equivalent.
3. If $Y \sim \text{gamma}(\alpha, \beta)$ and $\gamma = \frac{2}{\sqrt{\alpha}} \leq 4$, then $\sqrt{4\beta Y} - \sqrt{4\alpha - 1} \approx N(0, 1)$. See ex. 2.5.14 for a comparison of the first four moments. So approximating a translated gamma approximation with parameters α , β and x_0 , we also have $\Pr[S \leq s] \approx \Phi(\sqrt{4\beta(s - x_0)} - \sqrt{4\alpha - 1})$.
Show $\Pr[S \leq s] \approx \Phi\left(\sqrt{\frac{8}{\gamma} \frac{s - \mu}{\sigma} + \frac{16}{\gamma^2}} - \sqrt{\frac{16}{\gamma^2} - 1}\right)$ if $\alpha = \frac{4}{\gamma^2}, \beta = \frac{2}{\gamma\sigma}, x_0 = \mu - \frac{2\sigma}{\gamma}$.
Inversely, show $\Pr[S \leq x_0 + \frac{1}{4\beta}(y + \sqrt{4\alpha - 1})^2] \approx 1 - \varepsilon$ if $\Phi(y) = 1 - \varepsilon$,
as well as $\Pr\left[\frac{S - \mu}{\sigma} \leq y + \frac{\gamma}{8}(y^2 - 1) + y(\sqrt{1 - \gamma^2/16} - 1)\right] \approx \Phi(y)$.

4. Show that the translated gamma approximation as well as the NP approximation result in the normal approximation (CLT) if μ and σ^2 are fixed and $\gamma \downarrow 0$.
5. Approximate the critical values of a χ_{18}^2 distribution for $\varepsilon = 0.05, 0.1, 0.5, 0.9, 0.95$ with the NP approximation and compare the results with the exact values.
6. In the previous exercise, what is the result if the translated gamma approximation is used?
7. Use the identity ‘having to wait longer than x for the n th event’ \equiv ‘at most $n - 1$ events occur in $(0, x)$ ’ in a Poisson process to prove that $\Pr[Z > x] = \Pr[N < n]$ if $Z \sim \text{gamma}(n, 1)$ and $N \sim \text{Poisson}(x)$. How can this fact be used to calculate the translated gamma approximation?
8. Compare the exact critical values of a χ_{18}^2 distribution for $\varepsilon = 0.05, 0.1, 0.5, 0.9, 0.95$ with the approximations obtained in exercise 2.5.3.
9. An insurer’s portfolio contains 2 000 one-year life insurance policies. Half of them are characterized by a payment $b_1 = 1$ and a probability of dying within 1 year of $q_1 = 1\%$. For the other half, we have $b_2 = 2$ and $q_2 = 5\%$. Use the CLT to determine the minimum safety loading, as a percentage, to be added to the net premium to ensure that the probability that the total payment exceeds the total premium income is at most 5%.
10. As the previous exercise, but now using the NP approximation. Employ the fact that the third cumulant of the total payment equals the sum of the third cumulants of the risks.
11. Show that the right hand side of (2.60) is well-defined for all $x \geq -1$. What are the minimum and the maximum values? Is the function increasing? What happens if $x = 1$?
12. Suppose that X has expected value $\mu = 1000$ and standard deviation $\sigma = 2000$. Determine the skewness γ if (i) X is normal, (ii) $X/\phi \sim \text{Poisson}(\mu/\phi)$, (iii) $X \sim \text{gamma}(\alpha, \beta)$, (iv) $X \sim \text{inverse Gaussian}(\alpha, \beta)$ or (v) $X \sim \text{lognormal}(v, \tau^2)$. Show that the skewness is infinite if (vi) $X \sim \text{Pareto}$. See also Table A.
13. A portfolio consists of two types of contracts. For type k , $k = 1, 2$, the claim probability is q_k and the number of policies is n_k . If there is a claim, then its size is x with probability $p_k(x)$:

	n_k	q_k	$p_k(1)$	$p_k(2)$	$p_k(3)$
Type 1	1000	0.01	0.5	0	0.5
Type 2	2000	0.02	0.5	0.5	0

Assume that the contracts are independent. Let S_k denote the total claim amount of the contracts of type k and let $S = S_1 + S_2$. Calculate the expected value and the variance of a contract of type k , $k = 1, 2$. Then, calculate the expected value and the variance of S . Use the CLT to determine the minimum capital that covers all claims with probability 95%.

14. [♠] Let $U \sim \text{gamma}(\alpha, 1)$, $Y \sim N(\sqrt{4\alpha - 1}, 1)$ and $T = \sqrt{4U}$. Show that $E[U^t] = \Gamma(\alpha + t)/\Gamma(\alpha)$, $t > 0$. Then show that $E[Y^j] \approx E[T^j]$, $j = 1, 3$, by applying $\Gamma(\alpha + 1/2)/\Gamma(\alpha) \approx \sqrt{\alpha - 1/4}$ and $\alpha\Gamma(\alpha) = \Gamma(\alpha + 1)$. Also, show that $E[Y^2] = E[T^2]$ and $E[Y^4] = E[T^4] - 2$.
15. [♠] A justification for the ‘correction for continuity’, see Example 2.5.3, used to approximate cdf of integer valued random variables by continuous ones, goes as follows. Let G be the continuous cdf of some non-negative random variable, and construct cdfs H by $H(k + \varepsilon) = G(k + 0.5)$, $k = 0, 1, 2, \dots$, $0 \leq \varepsilon < 1$. Using the *midpoint rule* with intervals of length 1 to approximate the right hand side of (1.33) at $d = 0$, show that the means of G and H are about equal. Conclude that if G is a continuous cdf that is a plausible candidate for approximating the discrete cdf F and has the same mean as F , by taking $F(x) := G(x + 0.5)$ one gets an approximation with the proper mean value. [Taking $F(x) = G(x)$ instead, one gets a mean that is about $\mu + 0.5$ instead of μ . Thus very roughly speaking, each tail probability of the sum approximating (1.33) will be too big by a factor $\frac{1}{2\mu}$.]
16. To get a feel for the approximation error as opposed to the error caused by errors in the estimates of μ , σ and γ needed for the NP approximation and the gamma approximation,

recalculate Example 2.5.5 if the following parameters are changed: (i) $\mu = 10100$ (ii) $\sigma = 1020$ (iii) $\mu = 10100$ and $\sigma = 1020$ (iv) $\gamma = 1.03$. Assume that the remaining parameters are as they were in Example 2.5.5.

17. The function `pNormalPower`, when implemented carelessly, sometimes produces the value `NaN` (not a number). Why and when could that happen? Build in a test to cope with this situation more elegantly.
18. Compare the results of the translated gamma approximation with an exact `Poisson(1)` distribution using the calls `pTransGam(0:10, 1, 1, 1)` and `ppois(0:10, 1)`. To see the effect of applying a correction for continuity, compare also with the result of `pTransGam(0:10+0.5, 1, 1, 1)`.
19. Repeat the previous exercise, but now for the Normal Power approximation.
20. Note that we have prefixed the (approximate) cdf with `p`, as is customary in R. Now write quantile functions `qTransGam` and `qNormalPower`, and do some testing.
21. Prove (2.64) and (2.65).

Section 2.6

1. In the situation of Section 2.6, calculate the probability that B will be insufficient for retentions $d \in [2, 3]$. Give numerical results for $d = 2$ and $d = 3$ if $B = 405$.
2. Determine the retention $d \in [2, 3]$ that minimizes this probability for $B = 405$. Which retention is optimal if $B = 404$?
3. Calculate the probability that B will be insufficient if $d = 2$ by using the NP approximation.

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