

Contents

1	Introduction	1
1.1	Initial Situation	1
1.2	Prototype Concepts for Active Microsystems	4
1.3	Scientific Development	6
1.4	Outline	7
 Part I Design and Construction		
2	Electromagnetic Design of Microactuators	11
2.1	Forms of Electromagnetic Microactuators	11
2.2	Design and Construction	12
2.3	Material Properties	13
2.4	Coil Forms	14
2.5	Functional Principles	14
2.6	Design of Micromotors	19
	References	28
3	Drive Systems Based on Electromagnetic Microactuators .	29
3.1	Configuration of Drive Systems Based on Electromagnetic Microactuators	29
3.2	Power Supply	30
3.3	Current Command Generation	38
3.4	Position Control	40
	References	47
4	Modular Computer Aided Design Environment for Active Microsystems	49
4.1	Introduction	49
4.2	Phase of Preliminary Design	52
4.3	3D-Model Synthesis and Optimization	56

4.4 Synthesis and Optimization of Processes and Process Sequences	58
References	66

Part II Guiding and Measuring in Active Microsystems

5 Wear Behavior in Microactuator Interfaces	69
5.1 Introduction	69
5.2 Test Systems.....	70
5.3 Fabrication Process of Tribological Surfaces	77
5.4 Experimental Investigations.....	79
5.5 Conclusion	86
References	86
6 Friction Behavior in Microsystems	89
6.1 Introduction	89
6.2 Preparation of Microguides and Bearings	90
6.3 Characterization	93
6.4 Results.....	97
6.5 Conclusion	106
References	107
7 Active Linear Guiding Concepts for Microsystems	109
7.1 Introduction	109
7.2 Active Aerostatic Guides for Microsystems.....	110
7.3 Active Magnetic Guides for Microsystems	117
7.4 Capacitive Displacement Sensors for Active Guides	121
7.5 Conclusion	125
References	126
8 Design of Sensors for Position Control of Microactuators .	127
8.1 Introduction, Requirements and Measurement Principle	127
8.2 Simulation of Integrated Laser Beam 3×3 Couplers	129
8.3 Production of Integrated 3×3 Couplers in Glass	132
8.4 Beam Guiding by Refractive and Diffractive Elements: Grating, Prism, Lenses	134
8.5 Signal Detection.....	137
8.6 Realtime Signal Processing	138
8.7 Alignment and Fixing of Optical Components	141
8.8 Summary.....	143
References	144

9	Tactile Dimensional Micrometrology	145
9.1	Introduction	145
9.2	3D Microprobes	146
9.3	Calibration of Probing Forces	157
9.4	Dimensional Standards for Micro Metrology	160
	References	163

Part III Manufacturing and Fabrication

10	Fabrication of Magnetic Layers for Electromagnetic Microactuators	167
10.1	Introduction	167
10.2	Fabrication Technologies	169
10.3	Test Systems	171
10.4	Experimental Investigations on Soft Magnetic Materials	173
10.5	Experimental Investigation on Hard Magnetic Materials	179
10.6	System Integration Aspects	184
10.7	Conclusion	186
	References	186
11	Fabrication of Excitation Coils for Electromagnetic Microactuators	189
11.1	Introduction	189
11.2	Photoresist Pattern Creation	191
11.3	Electroplating of Cu Microcoils	196
11.4	Insulation	197
11.5	Integration of Coils into Microactuators	198
11.6	Conclusion	205
	References	205
12	Development and Fabrication of Electromagnetic Microactuators	207
12.1	Introduction	207
12.2	Linear VR Stepper Motor	209
12.3	Rotating VR Stepper Motor	215
12.4	Rotating Synchronous Micro Motors	219
12.5	Conclusion and Outlook	223
	References	224
13	Development and Fabrication of Linear and Multi-Axis Microactuators	225
13.1	Introduction	225
13.2	Linear VR Microstep Motor	226
13.3	Linear Hybrid Microstep Motor	227
13.4	Linear Synchronous Micromotor	230
13.5	xy-Actuator Investigations	234

13.6	VR Micro- and Nanopositionier for xy-Actuators	235
13.7	Experimental	241
13.8	Conclusion	242
	References	243
14	Micromachining of Parts for Microsystems	245
14.1	Introduction	245
14.2	Microgrinding	246
14.3	Microgrinding of Boreholes	260
14.4	Conclusions	262
	References	264
 Part IV Microassembly		
15	Size-Adapted Manipulation Robots for Microassembly	269
15.1	Introduction	269
15.2	Size-Adapted Robot for Microassembly	272
15.3	Miniaturized Robot for Desktop Factories	277
15.4	Conclusion	285
	References	286
16	Tools for Handling and Assembling of Microparts	287
16.1	Introduction	287
16.2	Electrostatic Forces in Microhandling Processes	289
16.3	Mechanical Microgrippers with Integrated Actuators	297
16.4	Pneumatically Driven Auxiliary Microtools	305
	References	307
17	Stereophotogrammetry in Microassembly	309
17.1	Introduction	309
17.2	Photogrammetry	310
17.3	Conclusions	325
	References	326
18	Use of Hot Melt Adhesives for the Assembly of Microsystems	327
18.1	Adhesive Bonding as Micro Joining Technology	327
18.2	Properties of Hot Melt Adhesives	328
18.3	Adhesive System Selection Criteria	329
18.4	Different Particle Shapes of Micro-Scale Hot Melt Adhesives	331
18.5	Application Methods for Micro-Scale Hot Melt Adhesives	333
18.6	Properties of Hot Melt Adhesive Bonds	339
18.7	Conclusion	342
	References	343

19 Design of a Microassembly Process Based on Hot Melt Adhesives	345
19.1 Introduction	345
19.2 Process Design for the Joining with Hot Melt Adhesives	348
19.3 Implementation of a Passive Heat Management	352
19.4 Implementation of Active Heat Management	358
19.5 Conclusion	362
References	363
20 Design of an Automated Assembly for Micro and Nano Actuators	365
20.1 Introduction	365
20.2 Assembly Concept for a Linear Microactuator with Levitation System	367
20.3 Assembly Concept for a xy-Micro- and Nanopositioner	369
20.4 Conclusion	371
Part V Industrial Applications	
21 Bistable Microvalve for Biomedical Usage	375
21.1 Introduction	375
21.2 Concept	377
21.3 Transfer of SFB Knowledge	379
21.4 Realization	379
21.5 Combination of the Valve Layers	387
21.6 Pre-Evaluation of the Intermediates	388
21.7 Summary and Prototype	390
21.8 Outlook	391
References	392
22 Microassembly Following the Desktop Factory Concept ...	393
22.1 Introduction	393
22.2 Miniaturized Components	397
22.3 New Prototype of the <i>Parvus</i> Robot	399
22.4 Experimental Verification	402
22.5 Conclusion	407
References	408
23 Automated Optical BGA-Inspection – AUTOBIN	411
23.1 Introduction	411
23.2 Specification of the Target System	416
References	422

24 Slider with Integrated Microactuator (SLIM) for Second Stage Actuation in Hard Disk Drives	423
24.1 Introduction:	423
24.2 Concept	424
24.3 Micromagnetics Design and Fabrication	426
24.4 Micromechanics Design and Fabrication	430
24.5 SLIM System Integration	432
24.6 Experimental Investigations	436
24.7 Conclusion and Outlook	438
References	439
Index	441

Design and Manufacturing of Active Microsystems

Buttgenbach, S.; Burisch, A.; Hesselbach, J. (Eds.)

2011, XII, 444 p., Hardcover

ISBN: 978-3-642-12902-5