

Differentialgleichungen

Lösung der DGL der Rechteckplatte mit trapezförmiger Teilflächenlast

Systemkennwerte

Abmessungen $l_x := 6.5$

$l_y := 3.5$

$$\alpha := \frac{l_y}{l_x} \quad \alpha = 0.538$$

Plattenstärke $t := 0.2$

Elastizitätsmodul $E := 3 \cdot 10^7$

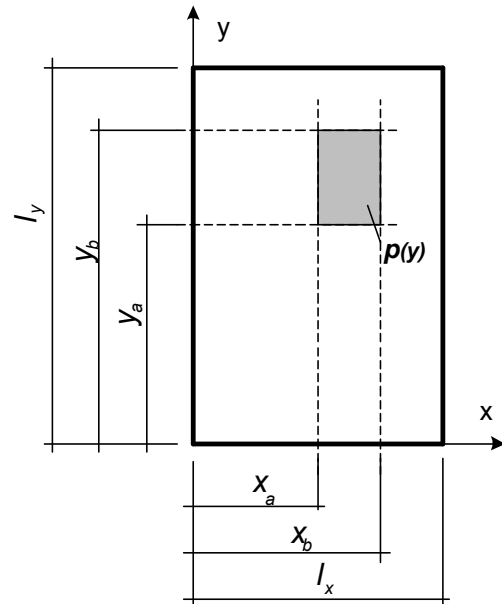
Querdehnzahl $\mu := 0.2$

Lagerung: Platte allseitig gelenkig gelagert

Last $y_a := 1$ $p_a := 2$

$y_b := 2.5$ $p_b := 10$

$x_a := 1$ $x_b := 3$



Plattensteifigkeit: $K := \frac{E \cdot t^3}{12 \cdot (1 - \mu^2)}$ $K = 2.083 \times 10^4$

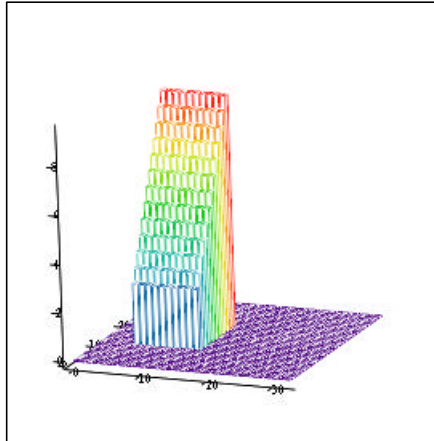
Diskretisierung $n_p := 32$ $h := \frac{l_x}{n_p}$ $h = 0.203$

$$i := 0..n_p \quad j := 0..n_p$$

$$LA(x, y, x_a, x_b, y_a, y_b, p_a, p_b) := \begin{cases} p_a + \frac{p_b - p_a}{y_b - y_a} \cdot (y - y_a) & \text{if } (y \geq y_a) \wedge (y \leq y_b) \wedge (x \geq x_a) \wedge (x \leq x_b) \\ 0 & \text{otherwise} \end{cases}$$

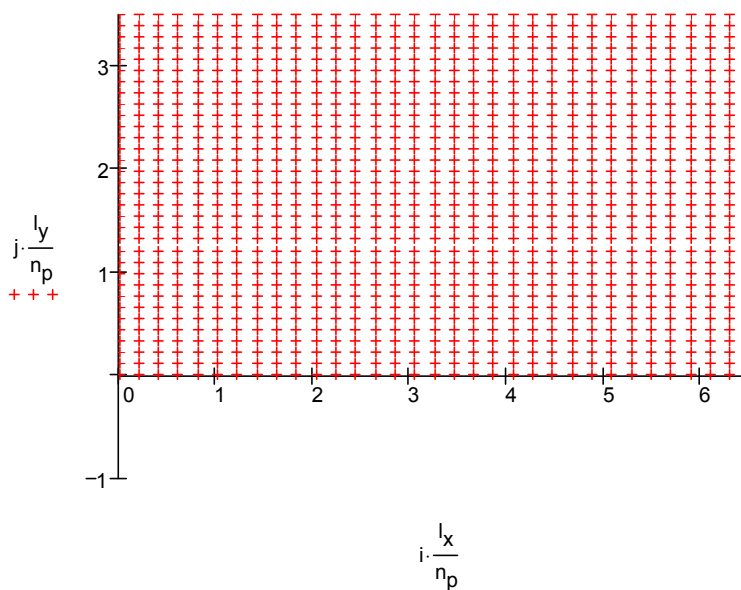
$$p_{i,j} := LA\left(\frac{l_x}{n_p} \cdot i, \frac{l_y}{n_p} \cdot j, x_a, x_b, y_a, y_b, p_a, p_b\right)$$

Last:



p

Gitter:



Koeffizienten

$$A_{i,j} := 1 \quad B_{i,j} := 1 \quad C_{i,j} := \frac{1}{\alpha^2} \quad D_{i,j} := \frac{1}{\alpha^2} \quad E_{i,j} := -2 \cdot \left(1 + \frac{1}{\alpha^2} \right)$$

$$S := p$$

Randbedingungen $U_{i,j} := 0$

Lösung der DGL

Spektralradius ($0 < r < 1$):

$$r := 1 - \frac{2 \cdot \pi}{n_p}$$

$r = 0.804$

$$M := \text{relax}(A, B, C, D, E, -S \cdot h^2, U, r)$$

$$W := \text{relax}\left(A, B, C, D, E, \frac{-M}{K} \cdot h^2, U, r\right)$$

Schnittgrößen

$$\begin{aligned} \text{Mom}(w, hx, hy, NN, K, \text{art}) := & \text{for } i \in 1..(NN-1) \\ & \text{for } j \in 1..(NN-1) \\ & \left[\begin{aligned} M_{i,j} \leftarrow & \left[\begin{aligned} & \left(\frac{w_{i-1,j} - 2 \cdot w_{i,j} + w_{i+1,j}}{hx^2} + \mu \cdot \frac{w_{i,j-1} - 2 \cdot w_{i,j} + w_{i,j+1}}{hy^2} \right) \text{ if } \text{art} = \text{"mx"} \\ & \left(\frac{w_{i,j-1} - 2 \cdot w_{i,j} + w_{i,j+1}}{hy^2} + \mu \cdot \frac{w_{i-1,j} - 2 \cdot w_{i,j} + w_{i+1,j}}{hx^2} \right) \text{ if } \text{art} = \text{"my"} \\ & \left[\frac{1-\mu}{4 \cdot hx \cdot hy} \cdot \left[(w_{i-1,j+1} + w_{i+1,j-1}) - (w_{i-1,j-1} + w_{i+1,j+1}) \right] \right] \text{ if } \text{art} = \text{"mxy"} \end{aligned} \right] \\ M_{0,j} \leftarrow & 0 \\ M_{NN,j} \leftarrow & 0 \\ M_{i,0} \leftarrow & 0 \\ M_{i,NN} \leftarrow & 0 \\ M_{0,0} \leftarrow & 0 \\ M_{NN,NN} \leftarrow & 0 \\ M_{NN,0} \leftarrow & 0 \\ M_{0,NN} \leftarrow & 0 \\ M \leftarrow & M \cdot (-K) \end{aligned} \right. \end{aligned}$$

Durchbiegungen w:

$$\max(W) = 0.12 \cdot 10^{-3} \quad \min(W) = 0$$

Biegemomente m_x

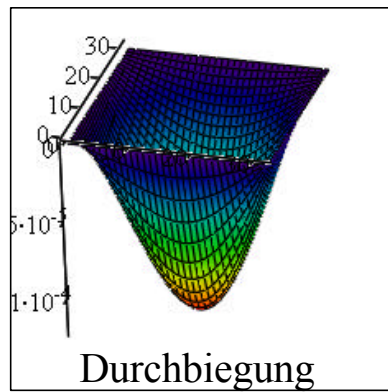
$$M_X := \text{Mom}\left(W, \frac{l_x}{n_p}, \frac{l_y}{n_p}, n_p, K, \text{"mx"}\right) \quad \max(M_X) = 1.734 \quad \min(M_X) = -0.095$$

Biegemomente m_y

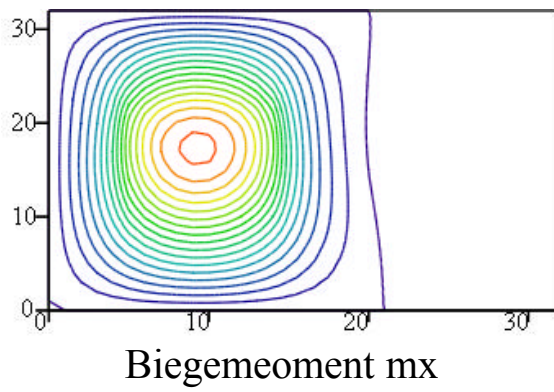
$$M_Y := \text{Mom}\left(W, \frac{l_x}{n_p}, \frac{l_y}{n_p}, n_p, K, \text{"my"}\right) \quad \max(M_Y) = 2.573 \quad \min(M_Y) = 0$$

Drillmomente m_{xy}

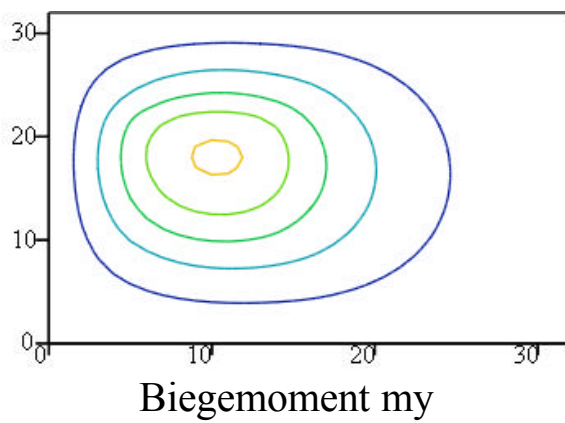
$$M_XY := \text{Mom}\left(W, \frac{l_x}{n_p}, \frac{l_y}{n_p}, n_p, K, \text{"mxy"}\right) \quad \max(M_XY) = 1.11 \quad \min(M_XY) = -1.228$$



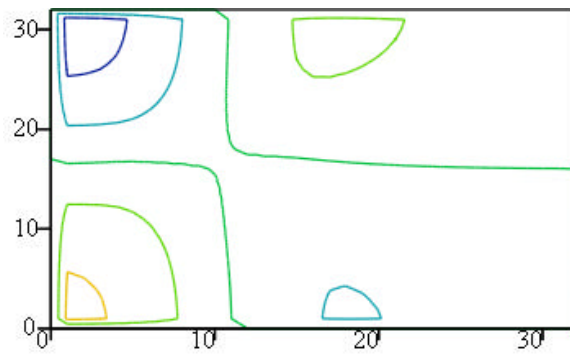
w



M_X



M_Y



Drillmomente

M_{XY}