

Chapter 1

The Riemannian adiabatic limit

The purpose of this chapter is to study the adiabatic limit of the Levi-Civita connection on a fibred manifold. This study was initiated in [B86a], and continued in Bismut-Cheeger [BC89], Berline-Getzler-Vergne [BeGeV92], Berthomieu-Bismut [BerB94] and Bismut [B97].

This chapter is organized as follows. In Section 1.1, we introduce a smooth proper submersion $p : M \rightarrow S$.

In Section 1.2, we construct a family of Riemannian metrics g_ϵ^{TM} , and we study the limit as $\epsilon \rightarrow 0$ of the corresponding Levi-Civita connection and of related tensors.

Finally, in Section 1.3, we construct a trilinear form ρ_0 on the tangent bundle TM .

1.1 A smooth submersion

Let M, S be smooth manifolds. Let $p : M \rightarrow S$ be a smooth submersion with compact fibre X . Let $TX = TM/S$ denote the relative tangent bundle. We have the exact sequence of smooth vector bundles on M ,

$$0 \rightarrow TX \longrightarrow TM \xrightarrow{p_*} p^*TS \rightarrow 0. \quad (1.1.1)$$

Let g^{TM} be a smooth Riemannian metric on TM , let g^{TX} be its restriction to TX . Let $T^H M$ be the orthogonal bundle to TX in TM with respect to g^{TM} , so that TM splits orthogonally as

$$TM = TX \oplus T^H M. \quad (1.1.2)$$

Clearly p_* induces the isomorphism

$$T^H M = p^*TS. \quad (1.1.3)$$

By (1.1.2), (1.1.3), we get

$$TM = TX \oplus p^*TS. \quad (1.1.4)$$

If $A \in TS$, let $A^H \in T^H M$ correspond to A via (1.1.3).

Let $g^{T^H M}$ be the metric induced by g^{TM} on $T^H M$. Then $g^{T^H M}$ can be viewed as a metric on p^*TS .

Let $P^{TX}, P^{T^H M}$ be the projections from TM on $TX, T^H M$ with respect to the splitting (1.1.2).

Let $\nabla^{TM, LC}$ be the Levi-Civita connection on (TM, g^{TM}) .

By the results of [B86a, section 1], $(T^H M, g^{TX})$ uniquely determines a metric preserving connection $\nabla^{TX, LC}$ on TX . The connection $\nabla^{TX, LC}$ is the projection of $\nabla^{TM, LC}$ on TX with respect to the splitting (1.1.2), the crucial point being that it only depends on $(T^H M, g^{TX})$. The restriction of $\nabla^{TX, LC}$ to one given fibre X is the Levi-Civita connection on the tangent bundle of the fibre.

If A is a smooth section of TS , let L_{A^H} be the Lie derivative operator associated with the vector field A^H . Then L_{A^H} acts on the tensor algebra of TX , and this action is a tensor also in $A \in TS$. By [B97, Theorem 1.1], if A, E are smooth sections of TS, TX , then

$$\nabla_{A^H}^{TX, LC} E = [A^H, E] + \frac{1}{2} (g^{TX})^{-1} (L_{A^H} g^{TX}) E. \quad (1.1.5)$$

Let g^{TS} be a smooth Riemannian metric on TS . Let $\nabla^{TS, LC}$ be the Levi-Civita connection on (TS, g^{TS}) . We can write $g^{T^H M}$ in the form

$$g^{T^H M} = g^{TS} k, \quad (1.1.6)$$

where k is a smooth section of $p^* \text{End}(TS)$ over M which is self-adjoint and positive with respect to g^{TS} .

1.2 The limit of the Levi-Civita connection as $\epsilon \rightarrow 0$

For $\epsilon > 0$, let g_ϵ^{TM} be the metric on TM given by

$$g_\epsilon^{TM} = g^{TM} + \frac{1}{\epsilon} p^* g^{TS}. \quad (1.2.1)$$

Using (1.1.4), (1.1.6), we can rewrite (1.2.1) in the form

$$g_\epsilon^{TM} = g^{TX} \oplus g^{TS} \left(\frac{1}{\epsilon} + k \right). \quad (1.2.2)$$

Then g_ϵ^{TM} still induces the metric g^{TX} on TX , and $T^H M$ is the orthogonal bundle to TX with respect to g_ϵ^{TM} . Let $\nabla_\epsilon^{TM, LC}$ be the Levi-Civita connection on TM with respect to the metric g_ϵ^{TM} . By the above, $\nabla_\epsilon^{TM, LC}$ projects on TX as the fixed connection $\nabla^{TX, LC}$.

With respect to the splitting (1.1.4) of TM , $\nabla_\epsilon^{TM,LC}$ can be written in the form

$$\nabla_\epsilon^{TM,LC} = \begin{bmatrix} \nabla^{TX,LC} & S_\epsilon^{TX,LC} \\ -S_\epsilon^{TX,LC*} & \nabla_\epsilon^{TS} \end{bmatrix}. \quad (1.2.3)$$

Let $\nabla_{s,\epsilon}^{TS}$ be the connection on p^*TS ,

$$\nabla_{s,\epsilon}^{TS} = \nabla^{TS,LC} + \frac{\epsilon}{2} (1 + \epsilon k)^{-1} \nabla^{TS,LC} k. \quad (1.2.4)$$

Set

$$\nabla_{s,\epsilon}^{TM,LC} = \begin{bmatrix} \nabla^{TX,LC} & 0 \\ 0 & \nabla_{s,\epsilon}^{TS} \end{bmatrix}. \quad (1.2.5)$$

Then $\nabla_{s,\epsilon}^{TM,LC}$ is an Euclidean connection on (TM, g_ϵ^{TM}) .

Set

$$\nabla_s^{TM,LC} = \begin{bmatrix} \nabla^{TX,LC} & 0 \\ 0 & \nabla^{TS,LC} \end{bmatrix}. \quad (1.2.6)$$

Then $\nabla_s^{TM,LC}$ is an Euclidean connection on $TX \oplus p^*TS$ equipped with the metric $g^{TX} \oplus p^*g^{TS}$.

By (1.2.4), (1.2.5), as $\epsilon \rightarrow 0$,

$$\nabla_{s,\epsilon}^{TM,LC} = \nabla_s^{TM,LC} + \mathcal{O}(\epsilon). \quad (1.2.7)$$

In (1.2.7), $\mathcal{O}(\epsilon)$ indicates that if K is a compact subset of M , for any $k \in \mathbf{N}$, the coefficients of the considered operator and its derivatives of order $\leq k$ can be dominated by $C_{K,k}\epsilon$. In the whole book, a similar notation will be used for other tensors.

Let $T_{s,\epsilon}, T_s$ be the torsions of $\nabla_{s,\epsilon}^{TM,LC}, \nabla_s^{TM,LC}$. Since $\nabla^{TX,LC}$ is fibrewise torsion free, $T_{s,\epsilon}, T$ both vanish on $TX \times TX$. By (1.2.7), we get

$$T_{s,\epsilon} = T_s + \mathcal{O}(\epsilon). \quad (1.2.8)$$

By (1.2.4), for $A, B \in TM$,

$$\frac{\partial}{\partial \epsilon} p_* T_{s,\epsilon}|_{\epsilon=0} (A, B) = \frac{1}{2} (\nabla_A^{TS} k p_* B - \nabla_B^{TS} k p_* A). \quad (1.2.9)$$

By (1.2.6), T_s takes its values in TX . Since ∇^{TS} is torsion free, if $A, B \in TS$,

$$T_s (A^H, B^H) = -P^{TX} [A^H, B^H]. \quad (1.2.10)$$

By [B97, Theorem 1.1] or by (1.1.5), if $A \in TS, E \in TX$,

$$T_s (A^H, E) = \frac{1}{2} (g^{TX})^{-1} (L_{A^H} g^{TX}) E. \quad (1.2.11)$$

In particular if $A \in TS$, and if $E, F \in TX$, then

$$\langle T_s (A^H, E), F \rangle_{g^{TX}} = \langle E, T_s (A^H, F) \rangle_{g^{TX}}. \quad (1.2.12)$$

By the above, we recover the known fact that the tensor T_s depends only on $(g^{TX}, T^H M)$.

Set

$$S_{s,\epsilon}^{TM} = \nabla_\epsilon^{TM,LC} - \nabla_{s,\epsilon}^{TM,LC}. \quad (1.2.13)$$

By (1.2.3), (1.2.5), $S_{s,\epsilon}^{TM}$ is of the form

$$S_{s,\epsilon}^{TM} = \begin{bmatrix} 0 & S_\epsilon^{TX,LC} \\ -S_\epsilon^{TX,LC*} & S_\epsilon^{TS} \end{bmatrix}. \quad (1.2.14)$$

Since $\nabla_\epsilon^{TM,LC}$ is torsion free, if $A, B \in TM$, then

$$T_{s,\epsilon}(A, B) = -S_{s,\epsilon}^{TM}(A)B + S_{s,\epsilon}^{TM}(B)A. \quad (1.2.15)$$

Moreover, if $A, B, C \in TM$, we have the classical identity

$$\begin{aligned} 2\langle S_{s,\epsilon}^{TM}(A)B, C \rangle_{g_\epsilon^{TM}} + \langle T_{s,\epsilon}(A, B), C \rangle_{g_\epsilon^{TM}} \\ + \langle T_{s,\epsilon}(C, A), B \rangle_{g_\epsilon^{TM}} - \langle T_{s,\epsilon}(B, C), A \rangle_{g_\epsilon^{TM}} = 0. \end{aligned} \quad (1.2.16)$$

Using (1.2.8), (1.2.9), the fact that T_s takes its values in TX , and (1.2.16), we find that there is a smooth section $S^{TX,LC}$ of $T^*M \otimes \text{Hom}(p^*TS, TX)$ such that as $\epsilon \rightarrow 0$,

$$S_\epsilon^{TX,LC} = S^{TX,LC} + \mathcal{O}(\epsilon), \quad S_\epsilon^{TX,LC*} = \mathcal{O}(\epsilon), \quad S_\epsilon^{TS} = \mathcal{O}(\epsilon). \quad (1.2.17)$$

In the sequel, we identify $S^{TX,LC}$ with the corresponding element of $T^*M \otimes \text{End}(TM)$ that vanishes on TX . By (1.2.14), (1.2.17), as $\epsilon \rightarrow 0$,

$$S_{s,\epsilon}^{TM} = S^{TX,LC} + \mathcal{O}(\epsilon). \quad (1.2.18)$$

By (1.2.8), (1.2.15), and (1.2.17), if $A, B \in TM$,

$$T_s(A, B) = -S^{TX,LC}(A)P^{T^H M}B + S^{TX,LC}(B)P^{T^H M}A. \quad (1.2.19)$$

By (1.2.16), (1.2.18), if $A \in TM, B \in TS, C \in TX$, then

$$\begin{aligned} 2\langle S^{TX,LC}(A)B^H, C \rangle_{g^{TX}} + \langle T_s(A, B^H), C \rangle_{g^{TX}} + \left\langle \frac{\partial}{\partial \epsilon} T_{s,\epsilon}|_{\epsilon=0}(C, A), B^H \right\rangle_{g^{TS}} \\ - \langle T_s(B^H, C), P^{TX}A \rangle_{g^{TX}} - \left\langle \frac{\partial}{\partial \epsilon} T_{s,\epsilon}|_{\epsilon=0}(B^H, C), P^{T^H M}A \right\rangle_{g^{TS}} = 0. \end{aligned} \quad (1.2.20)$$

By (1.2.9), we can rewrite (1.2.20) in the form

$$\begin{aligned} 2\langle S^{TX,LC}(A)B^H, C \rangle_{g^{TX}} + \langle T_s(A, B^H), C \rangle_{g^{TX}} \\ - \langle T_s(B^H, C), P^{TX}A \rangle_{g^{TX}} + \langle \nabla_C^{TS} k B, p_* A \rangle_{g^{TS}} = 0. \end{aligned} \quad (1.2.21)$$

Set

$$\nabla_0^{TM,LC} = \nabla_s^{TM,LC} + S^{TX,LC}. \quad (1.2.22)$$

Equivalently,

$$\nabla_0^{TM,LC} = \begin{bmatrix} \nabla^{TX,LC} & S^{TX,LC} \\ 0 & \nabla^{TS,LC} \end{bmatrix}. \quad (1.2.23)$$

By (1.2.7), (1.2.13), and (1.2.18), as $\epsilon \rightarrow 0$,

$$\nabla_\epsilon^{TM,LC} = \nabla_0^{TM,LC} + \mathcal{O}(\epsilon). \quad (1.2.24)$$

Since $\nabla_\epsilon^{TM,LC}$ is torsion free, $\nabla_0^{TM,LC}$ is also torsion free. Equation (1.2.19) is a reformulation of this fact.

1.3 The trilinear form ρ_0

Definition 1.3.1. For $A, B, C \in TM$, set

$$\rho_\epsilon(A, B, C) = \langle S_{s,\epsilon}^{TM}(A) B, C \rangle_{g_\epsilon^{TM}}. \quad (1.3.1)$$

If $A, B, C \in TM$, let $\rho_0(A, B, C) \in \mathbf{R}$ be defined by

$$\begin{aligned} 2\rho_0(A, B, C) &+ \langle T_s(A, B), P^{TX}C \rangle_{g^{TX}} + \langle T_s(C, A), P^{TX}B \rangle_{g^{TX}} \\ &- \langle T_s(B, C), P^{TX}A \rangle_{g^{TX}} - \langle \nabla_B^{TS} k p_* A, p_* C \rangle_{g^{TS}} + \langle \nabla_C^{TS} k p_* A, p_* B \rangle_{g^{TS}} = 0. \end{aligned} \quad (1.3.2)$$

Proposition 1.3.2. As $\epsilon \rightarrow 0$,

$$\rho_\epsilon = \rho_0 + \mathcal{O}(\epsilon). \quad (1.3.3)$$

Moreover, if $A \in TX, B, C \in TM$, $\rho_0(A, B, C)$ does not depend on g^{TS} , and is given by

$$\begin{aligned} 2\rho_0(A, B, C) &+ \langle T_s(A, B), P^{TX}C \rangle_{g^{TX}} + \langle T_s(C, A), P^{TX}B \rangle_{g^{TX}} \\ &- \langle T_s(B, C), P^{TX}A \rangle_{g^{TX}} = 0. \end{aligned} \quad (1.3.4)$$

Proof. Equation (1.3.3) follows from (1.2.9), (1.2.16), and (1.3.1). When $A \in TX$, $p_* A = 0$, and the last two terms in the left-hand side of (1.3.2) do vanish, so that we get (1.3.4). This shows that $\rho_0(A, B, C)$ does not depend on g^{TS} . The proof of our proposition is completed. \square

Definition 1.3.3. Let $S_0^{TM} \in T^*M \otimes \text{End}(TM)$ be such that if $A, B, C \in TM$, then

$$\langle S_0^{TM}(A) B, C \rangle_{g^{TX} \oplus g^{TS}} = \rho_0(A, B, C). \quad (1.3.5)$$

By (1.2.21), (1.3.2), S_0^{TM} can be written in the form

$$S_0^{TM} = \begin{bmatrix} 0 & S^{TX,LC} \\ -S^{TX,LC*} & S^{TS} \end{bmatrix}. \quad (1.3.6)$$

As the notation indicates, $S^{TX,LC*}$ is the adjoint of $S^{TX,LC}$.

Remark 1.3.4. The trilinear form ρ_0 was already obtained in [B86a, section 1 c)] when the metric g^{TM} defines a Riemannian submersion.

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