

# Contents

<b>1</b>	<b>Biological Models</b>	<b>1</b>
1.1	Introduction	3
1.2	Biological Foundation	5
1.3	Hodgkin-Huxley	6
1.4	Fitzhugh-Nagumo	7
1.5	Eckhorn Model	9
1.6	Rybak Model	10
1.7	Parodi Model	10
1.8	Summary	11
<b>2</b>	<b>Programming in Python</b>	<b>13</b>
2.1	Environment	13
2.1.1	Command Interface	14
2.1.2	IDLE	14
2.1.3	Establishing a Working Environment	14
2.2	Data Types and Simple Math	15
2.3	Tuples, Lists, and Dictionaries	16
2.3.1	Tuples	16
2.3.2	Lists	17
2.3.3	Dictionaries	18
2.4	Slicing	19
2.5	Strings	20
2.5.1	String Functions	21
2.5.2	Type Casting	23
2.6	Control	23
2.7	Input and Output	25
2.7.1	Basic Files	25
2.7.2	Pickle	26
2.8	Functions	27
2.9	Modules	28
2.10	Object Oriented Programming	30
2.10.1	Content of a Class	30
2.10.2	Operator Definitions	30

2.10.3	Inheritance . . . . .	31
2.11	Error Checking . . . . .	32
2.12	Summary . . . . .	33
<b>3</b>	<b>NumPy, SciPy and Python Image Library . . . . .</b>	<b>35</b>
3.1	NumPy . . . . .	35
3.1.1	Creating Arrays . . . . .	35
3.1.2	Converting Arrays . . . . .	38
3.1.3	Matrix: Vector Multiplications . . . . .	38
3.1.4	Justification for Arrays . . . . .	39
3.1.5	Data Types . . . . .	41
3.1.6	Sorting . . . . .	43
3.1.7	Conversions to Strings and Lists . . . . .	45
3.1.8	Changing the Matrix . . . . .	47
3.1.9	Advanced Slicing . . . . .	47
3.2	SciPy . . . . .	49
3.3	Designing in Numpy . . . . .	52
3.4	Python Image Library . . . . .	54
3.4.1	Reading an Image . . . . .	54
3.4.2	Writing an Image . . . . .	55
3.4.3	Transforming an Image . . . . .	56
3.5	Summary . . . . .	56
<b>4</b>	<b>The PCNN and ICM . . . . .</b>	<b>57</b>
4.1	The PCNN . . . . .	57
4.1.1	Original Model . . . . .	57
4.1.2	Implementing in Python . . . . .	59
4.1.3	Spiking Behaviour . . . . .	61
4.1.4	Collective Behaviour . . . . .	64
4.1.5	Time Signatures . . . . .	66
4.1.6	Neural Connections . . . . .	67
4.1.7	Fast Linking . . . . .	70
4.1.8	Models in Analogue Time . . . . .	73
4.2	The ICM . . . . .	74
4.2.1	Minimum Requirements . . . . .	75
4.2.2	ICM Theory . . . . .	76
4.2.3	Connections in the ICM . . . . .	77
4.2.4	Python Implementation . . . . .	83
4.3	Summary . . . . .	84
<b>5</b>	<b>Image Analysis . . . . .</b>	<b>87</b>
5.1	Pertinent Image Information . . . . .	87
5.2	Image Segmentation . . . . .	92

5.2.1	Blood Cells . . . . .	92
5.2.2	Mammography . . . . .	92
5.3	Adaptive Segmentation . . . . .	95
5.4	Focus and Foveation . . . . .	96
5.4.1	The Foveation Algorithm. . . . .	97
5.4.2	Target Recognition by a PCNN-Based Foveation Model . . . . .	99
5.5	Image Factorisation. . . . .	104
5.6	Summary . . . . .	105
<b>6</b>	<b>Feedback and Isolation . . . . .</b>	<b>107</b>
6.1	A Feedback PCNN . . . . .	107
6.2	Object Isolation . . . . .	109
6.2.1	Input Normalisation . . . . .	111
6.2.2	Creating the Filter . . . . .	111
6.2.3	Edge Enhancement of Pulse Images . . . . .	113
6.2.4	Correlation and Modifications . . . . .	114
6.2.5	Peak Detection . . . . .	116
6.2.6	Modifications to the Input and PCNN. . . . .	116
6.2.7	Drivers . . . . .	118
6.3	Dynamic Object Isolation . . . . .	119
6.4	Shadowed Objects . . . . .	119
6.5	Consideration of Noisy Images. . . . .	122
6.6	Summary . . . . .	125
<b>7</b>	<b>Recognition and Classification. . . . .</b>	<b>127</b>
7.1	Aircraft . . . . .	127
7.2	Aurora Borealis . . . . .	128
7.3	Target Identification: Binary Correlations . . . . .	129
7.4	Galaxies . . . . .	133
7.5	Hand Gestures . . . . .	137
7.6	Road Surface Inspection . . . . .	139
7.7	Numerals. . . . .	143
7.7.1	Data Set . . . . .	143
7.7.2	Isolating a Class for Training. . . . .	144
7.8	Generating Pulse Images . . . . .	145
7.8.1	Analysis of the Signatures . . . . .	146
7.9	Face Location and Identification. . . . .	148
7.10	Summary . . . . .	153
<b>8</b>	<b>Texture Recognition . . . . .</b>	<b>155</b>
8.1	Pulse Spectra . . . . .	155
8.2	Statistical Separation of the Spectra . . . . .	159

8.3	Recognition Using Statistical Methods . . . . .	160
8.4	Recognition of the Pulse Spectra via an Associative Memory . . . . .	161
8.5	Biological Application . . . . .	162
8.6	Texture Study . . . . .	167
8.7	Summary . . . . .	170
<b>9</b>	<b>Colour and Multiple Channels . . . . .</b>	<b>171</b>
9.1	The Model. . . . .	171
9.1.1	Colour Example . . . . .	172
9.1.2	Python Implementation . . . . .	176
9.2	Multi-Spectral Example. . . . .	180
9.3	Application of Colour Models . . . . .	183
9.4	Summary . . . . .	185
<b>10</b>	<b>Image Signatures . . . . .</b>	<b>187</b>
10.1	Image Signature Theory . . . . .	187
10.1.1	The PCNN and Image Signatures . . . . .	188
10.1.2	Colour Versus Shape. . . . .	189
10.2	The Signature of Objects. . . . .	189
10.3	The Signatures of Real Images. . . . .	191
10.4	Image Signature Database . . . . .	192
10.5	Computing the Optimal Viewing Angle . . . . .	193
10.6	Motion Estimation . . . . .	196
10.7	Summary . . . . .	198
<b>11</b>	<b>Logic . . . . .</b>	<b>201</b>
11.1	Maze Running and TSP . . . . .	201
11.2	Barcodes and Navigation. . . . .	203
11.3	Summary . . . . .	208
	<b>Appendix A: Image Converters . . . . .</b>	<b>209</b>
	<b>Appendix B: The Geometry Module. . . . .</b>	<b>215</b>
	<b>Appendix C: The Fractional Power Filter . . . . .</b>	<b>217</b>
	<b>Appendix D: Correlation . . . . .</b>	<b>219</b>
	<b>Appendix E: The FAAM . . . . .</b>	<b>223</b>
	<b>Appendix F: Principal Component Analysis . . . . .</b>	<b>227</b>

Contents	xix
<b>References</b> . . . . .	<b>229</b>
<b>Index</b> . . . . .	<b>235</b>

Image Processing using Pulse-Coupled Neural Networks

Applications in Python

Lindblad, Th.; Kinser, J.

2013, XXIV, 238 p., Hardcover

ISBN: 978-3-642-36876-9