

# Contents

<b>1</b>	<b>Introduction . . . . .</b>	<b>1</b>
1.1	Networked Control Systems . . . . .	1
1.1.1	Control over Networks Using a Finite Alphabet System . . . . .	3
1.1.2	Control over Networks Using Scheduling Strategies . . . . .	5
1.1.3	Control over Networks Using Discrete Plants with Packet Losses or Delays . . . . .	7
1.1.4	Control over Networks Using Packetized Control . . . . .	8
1.2	Model-Based Frameworks . . . . .	9
1.3	Event-Triggered Control . . . . .	14
 <b>Part I Stability</b>		
<b>2</b>	<b>Model-Based Control Systems: Stability . . . . .</b>	<b>19</b>
2.1	Fundamentals: Model-Based Control Architecture . . . . .	20
2.2	Continuous-Time LTI Systems: State Feedback . . . . .	21
2.3	Discrete-Time LTI Systems: State Feedback . . . . .	34
2.4	Alternative Conditions for Stability of MB-NCS . . . . .	42
2.4.1	A Lifting Approach for Stability of Discrete-Time MB-NCS . . . . .	43
2.4.2	Relation to Previous Results . . . . .	47
2.4.3	Additional Approaches for Stability of MB-NCS . . . . .	48
2.5	Notes and References . . . . .	51
<b>3</b>	<b>Model-Based Control Systems: Output Feedback and Delays . . . . .</b>	<b>55</b>
3.1	Output Feedback Using State Observers for Continuous Time Systems . . . . .	55
3.1.1	Separation Principle . . . . .	62
3.2	Output Feedback Using State Observers for Discrete Time Systems . . . . .	69
3.3	Network Induced Delays: Small Delay Case . . . . .	71

3.3.1	Continuous Time Systems with Delays . . . . .	72
3.3.2	Discrete Time Systems with Delays . . . . .	78
3.4	Network Induced Delays: Large Delay Case . . . . .	82
3.4.1	Continuous Time Systems . . . . .	82
3.4.2	Discrete-Time Systems . . . . .	86
3.5	Notes and References . . . . .	88
<b>4</b>	<b>Model-Based Control Systems with Intermittent Feedback . . . . .</b>	<b>91</b>
4.1	Continuous-Time Systems with State Feedback and Closed-Loop Mode . . . . .	92
4.1.1	Model-Based Control with Intermittent Feedback Architecture . . . . .	92
4.1.2	Stability of Continuous-Time MB-NCS with Intermittent Feedback . . . . .	93
4.2	A Different Approach: Fast-Slow Update Rates . . . . .	98
4.2.1	State Feedback . . . . .	99
4.2.2	Output Feedback . . . . .	102
4.3	Discrete-Time Systems with Intermittent Feedback . . . . .	106
4.3.1	State Feedback . . . . .	107
4.3.2	Discrete-Time Systems with Output Feedback . . . . .	109
4.4	Alternative Conditions for Stability of MB-NCS with Intermittent Feedback . . . . .	110
4.4.1	Relation to Previous Results . . . . .	111
4.5	Notes and References . . . . .	113
<b>5</b>	<b>Time-Varying and Stochastic Feedback Updates . . . . .</b>	<b>115</b>
5.1	Lyapunov Analysis of MB-NCS . . . . .	116
5.1.1	Lyapunov Stability . . . . .	118
5.2	Almost Sure Asymptotic Stability . . . . .	120
5.2.1	MB-NCS with Independent Identically Distributed Transmission Times . . . . .	121
5.2.2	MB-NCS with Markov Chain-Driven Transmission Times . . . . .	126
5.3	Mean Square Asymptotic Stability . . . . .	129
5.3.1	MB-NCS with Independent Identically Distributed Transmission Times . . . . .	129
5.3.2	MB-NCS with Markov Chain-Driven Transmission Times . . . . .	131
5.4	Notes and References . . . . .	132
<b>6</b>	<b>Event-Triggered Feedback Updates . . . . .</b>	<b>135</b>
6.1	Model-Based Event-Triggered Architecture . . . . .	136
6.1.1	A Preliminary Update Approach . . . . .	138
6.2	Event-Triggered Control Strategies . . . . .	141
6.2.1	Fixed Threshold Strategy . . . . .	141
6.2.2	Relative Threshold Strategy . . . . .	146
6.3	Systems with Network Induced Delays . . . . .	150

6.3.1	Updating the Model State Using Delayed Measurements . . . . .	152
6.4	Notes and References . . . . .	157
<b>7</b>	<b>Model-Based Nonlinear Control Systems . . . . .</b>	<b>159</b>
7.1	Constant Update Time Intervals . . . . .	160
7.1.1	Stability of a Class of Nonlinear MB-NCS . . . . .	160
7.1.2	Stability for a More General Class of Nonlinear MB-NCS . . . . .	165
7.2	Dissipative Nonlinear Discrete-Time Systems . . . . .	170
7.2.1	Dissipative System Theory . . . . .	172
7.2.2	Bounded Stability of Output Feedback Dissipative Systems . . . . .	174
7.3	Notes and References . . . . .	184
<b>8</b>	<b>Quantization Analysis and Design . . . . .</b>	<b>187</b>
8.1	Systems Using Static Quantizers . . . . .	188
8.1.1	Uniform Quantizers . . . . .	189
8.1.2	Logarithmic Quantizers . . . . .	192
8.2	Static Quantization, Event-Triggered Control, and Network Induced Delays . . . . .	195
8.3	Dynamic Quantization: A Different Way of Adapting to System Response . . . . .	203
8.4	Notes and References . . . . .	210
 <b>Part II Performance</b>		
<b>9</b>	<b>Optimal Control of Model-Based Event-Triggered Systems . . . . .</b>	<b>217</b>
9.1	Continuous-Time Robust LQR . . . . .	219
9.2	Discrete-Time Robust LQR . . . . .	222
9.3	Finite Horizon Optimal Control and Optimal Scheduling . . . . .	224
9.4	Notes and References . . . . .	231
<b>10</b>	<b>Performance Analysis Using Lifting Techniques . . . . .</b>	<b>233</b>
10.1	Performance Analysis of MB-NCS Using Continuous-Time Lifting . . . . .	234
10.1.1	Continuous Lifting Technique . . . . .	234
10.1.2	An $H_2$ Norm Characterization of a MB-NCS . . . . .	237
10.1.3	A Generalized $H_2$ Norm for MB-NCS . . . . .	240
10.2	Optimal Controller Design for MB-NCS . . . . .	245
10.3	Notes and References . . . . .	251
<b>11</b>	<b>Reference Input Tracking . . . . .</b>	<b>253</b>
11.1	Reference Input Tracking Controller . . . . .	254
11.2	Discretized Input Tracking Analysis . . . . .	256
11.2.1	Inter-Sample Behavior Analysis . . . . .	260
11.2.2	Reference Input Tracking for General System Output . . . . .	262

11.3	Output Feedback Tracking Using Different Dimension Models . . . . .	263
11.3.1	Output Feedback Tracking with Delays . . . . .	270
11.4	Notes and References . . . . .	275
<b>12</b>	<b>Adaptive Stabilization of Networked Control Systems . . . . .</b>	<b>277</b>
12.1	Adaptive Stabilization of Deterministic MB-NCS . . . . .	278
12.1.1	Stability . . . . .	279
12.1.2	Parameter Estimation . . . . .	283
12.2	Adaptive Stabilization of Stochastic MB-NCS . . . . .	286
12.3	Applications of Parameter Estimation and the Model-Based Approach . . . . .	288
12.3.1	Examples and Implementation Cases . . . . .	288
12.3.2	Actuator Fault Detection and Reconfiguration . . . . .	292
12.3.3	Identification and Rejection of Input Disturbances . . . . .	295
12.3.4	Identification and Stabilization of Switched Systems with State Jumps . . . . .	299
12.4	Parameter Identification Using Additional Measurements . . . . .	302
12.4.1	Parameter Identification Using Luenberger Observers . . . . .	302
12.4.2	Convergence Properties of the LTV-KF Used for Parameter Identification . . . . .	305
12.5	Notes and References . . . . .	306
<b>13</b>	<b>Multirate Systems . . . . .</b>	<b>309</b>
13.1	Multirate State Updates Using a Centralized Controller . . . . .	310
13.1.1	Model-Based Multirate Approach . . . . .	310
13.1.2	Updates with Network Constraints . . . . .	316
13.2	Two-Channel NCS . . . . .	318
13.2.1	Multirate Approach for Stability . . . . .	319
13.2.2	Two-Channel Networked Systems and Input Tracking . . . . .	324
13.3	Notes and References . . . . .	325
<b>14</b>	<b>Distributed Control Systems . . . . .</b>	<b>327</b>
14.1	Single-Rate Periodic Communication . . . . .	328
14.2	Multirate Periodic Communication . . . . .	332
14.3	Centralized Model-Based Event-Triggered Control . . . . .	338
14.4	Decentralized Model-Based Event-Triggered Control . . . . .	344
14.5	Notes and References . . . . .	351
	<b>Appendix . . . . .</b>	<b>353</b>
	<b>Bibliography . . . . .</b>	<b>365</b>
	<b>Index . . . . .</b>	<b>379</b>

Model-Based Control of Networked Systems

Garcia, E.; Antsaklis, P.; Montestruque, L.A.

2014, XVI, 382 p. 127 illus., 85 illus. in color., Hardcover

ISBN: 978-3-319-07802-1

A product of Birkhäuser Basel