

Contents

Part I Theoretical Background

Path Planning and Trajectory Planning Algorithms: A General Overview	3
Alessandro Gasparetto, Paolo Boscariol, Albano Lanzutti and Renato Vidoni	
Off-Line and On-Line Trajectory Planning	29
Zvi Shiller	
Open Architecture for Vision-Based Robot Motion Planning and Control	63
Theodor Borangiu, Florin Anton and Silvia Anton	
Grasping and Manipulation of Unknown Objects Based on Visual and Tactile Feedback	91
Robert Haschke	

Part II Motion Planning of Robotic Manipulators

Obstacle Avoidance with Industrial Robots	113
T. Petrič, A. Gams, N. Likar and L. Žlajpah	
Path Planning Kinematics Simulation of CNC Machine Tools Based on Parallel Manipulators	147
Luc Rolland	
Planning Automatic Surgical Tasks for a Robot Assistant	193
Enrique Bauzano Nuñez, Belen Estebanez Campos, Isabel Garcia Morales and Víctor F. Muñoz Martinez	

Part III Motion and Operation Planning for Wheeled Robots

Motion Planning Using Fast Marching Squared Method	223
S. Garrido, L. Moreno and Javier V. Gómez	

Motion Planning of Large Scale Vehicles for Remote Material Transportation	249
Alberto Vale and Isabel Ribeiro	

Car-Like Robot Manoeuvre Generation	293
F. Gomez-Bravo	

Vehicle Autonomy Using Cooperative Perception for Mobility-on-Demand Systems	331
Seong-Woo Kim, Tirthankar Bandyopadhyay, Baoxing Qin, Zhuang Jie Chong, Wei Liu, Xiaotong Shen, Scott Pendleton, James Guo Ming Fu, Marcelo H. Ang Jr., Emilio Frazzoli and Daniela Rus	

Motion Planning of a Spherical Mobile Robot.	361
Qiang Zhan	

Part IV Motion Planning for Legged Robots

A Minimum Jerk-Impedance Controller for Planning Stable and Safe Walking Patterns of Biped Robots	385
Amira Aloulou and Olfa Boubaker	

Online Walking Pattern Generation Using FFT for Humanoid Robots	417
Kenji Hashimoto, Hideki Kondo, Hun-Ok Lim and Atsuo Takanishi	

Hexapod Walking Robot Locomotion	439
Franco Tedeschi and Giuseppe Carbone	

Part V Robot Cooperation and Interaction

Distributed Cooperation of Multiple UAVs for Area Monitoring Missions	471
José J. Acevedo, Begoña C. Arrue, Iván Maza and Anibal Ollero	

Robotic Manipulation Within the Underwater Mission Planning	
Context	495
Javier Pérez, Jorge Sales, Antonio Peñalver, J. Javier Fernández, Pedro J. Sanz, Juan C. García, Jose V. Martí, Raul Marín and David Fornas	
Erratum to: Motion and Operation Planning of Robotic Systems	E1
Giuseppe Carbone and Fernando Gomez-Bravo	

Motion and Operation Planning of Robotic Systems

Background and Practical Approaches

Carbone, G.; Gomez-Bravo, F. (Eds.)

2015, IX, 522 p. 352 illus., 256 illus. in color., Hardcover

ISBN: 978-3-319-14704-8