

Contents

1 Preliminaries	1
1.1 Basic Notations	1
1.2 The Consensus Problem	1
1.2.1 Algebraic Graph Theory	2
1.2.2 Network Model	3
1.2.3 The Static Average Consensus Problem	3
1.2.4 The Dynamic Average Consensus Problem	5
1.3 Convex Optimization	7
1.3.1 Convex Analysis	7
1.3.2 Constrained Optimization	8
1.3.3 Duality Theory	8
1.4 Noncooperative Game Theory	10
1.4.1 Potential Games	11
1.4.2 Constrained Games	12
1.5 Markov Chains	12
1.5.1 Stochastic Stability	13
1.6 Notes	14
References	16
2 Distributed Cooperative Optimization	21
2.1 Introduction	21
2.2 Problem Formulation	22
2.2.1 Subgradient Notions and Notations	23
2.3 Case (i): Absence of Equality Constraint	24
2.3.1 The DISTRIBUTED LAGRANGIAN PRIMAL-DUAL SUBGRADIENT ALGORITHM	28
2.3.2 A Numerical Example for the DISTRIBUTED LAGRANGIAN PRIMAL-DUAL SUBGRADIENT ALGORITHM	29

2.4	Case (ii): Identical Local Constraint Sets	31
2.4.1	The DISTRIBUTED PENALTY PRIMAL-DUAL SUBGRADIENT ALGORITHM	34
2.4.2	A Numerical Example for the DISTRIBUTED PENALTY PRIMAL-DUAL SUBGRADIENT ALGORITHM	36
2.5	Appendix	38
2.5.1	Convergence Analysis of the DISTRIBUTED LAGRANGIAN PRIMAL-DUAL SUBGRADIENT ALGORITHM	39
2.5.2	Convergence Analysis of the DISTRIBUTED PENALTY PRIMAL-DUAL SUBGRADIENT ALGORITHM	47
2.6	Notes	56
	References	57
3	Game Theoretic Optimal Sensor Deployment	59
3.1	Introduction.	59
3.2	Problem Formulation	60
3.2.1	Coverage Game.	60
3.2.2	Our Objective	64
3.2.3	Notations	64
3.3	Distributed Learning Algorithms	65
3.3.1	The COVERAGE LEARNING ALGORITHM.	65
3.3.2	The ASYNCHRONOUS COVERAGE LEARNING ALGORITHM	66
3.4	Convergence Analysis	68
3.4.1	Convergence Analysis of the COVERAGE LEARNING ALGORITHM	69
3.4.2	Convergence Analysis of the ASYNCHRONOUS COVERAGE LEARNING ALGORITHM	74
3.5	Numerical Examples.	80
3.5.1	A Numerical Example of the COVERAGE LEARNING ALGORITHM	81
3.5.2	A Numerical Example of the ASYNCHRONOUS COVERAGE LEARNING ALGORITHM	83
3.6	Notes	84
	References	87
4	Distributed Resilient Formation Control	91
4.1	Introduction.	91
4.2	Problem Formulation	92
4.2.1	The Operator-Vehicle Network	92
4.2.2	Model of Adversaries.	94
4.2.3	A Motivating Scenario	95
4.2.4	Prior Information About Adversaries and Objective	96
4.3	Preliminaries	97
4.3.1	A Coordinate Transformation	97
4.3.2	A Constrained Multiparametric Program	97

4.4	Distributed Attack-Resilient Algorithm	99
4.4.1	Algorithm Statement	99
4.4.2	The Resilience Properties	101
4.5	Convergence Analysis	102
4.6	Discussion	112
4.6.1	The Special Case of Consensus	112
4.6.2	Resilience to Denial-of-Service Attacks	112
4.6.3	The Issue of Solving the n -OC	113
4.6.4	Pros and Cons	113
4.6.5	Tradeoff Between Computation, Memory, and Communication Costs	114
4.7	Numerical Examples	114
4.8	Notes	115
	References	116
	Series Editor's Biographies	119
	Algorithm Index	121
	Index	123

Distributed Optimization-Based Control of Multi-Agent
Networks in Complex Environments

Zhu, M.; Martínez, S.

2015, XIII, 124 p. 24 illus., 23 illus. in color., Softcover

ISBN: 978-3-319-19071-6