

Chapter 2

Fixed Point Results and Their Applications in Right Multivariate Fractional Calculus

We introduce a fixed point iterative scheme and use it to approximate a solution of a nonlinear operator equation. Applications are suggested involving in particular right multivariate fractional calculus. It follows [8].

2.1 Introduction

Let B_1, B_2 denote Banach spaces and Ω be a subset of B_1 . Let also $\mathcal{L}(B_1, B_2)$ stand for the space of bounded linear operators from B_1 into B_2 .

Problems in applied sciences, engineering and other disciplines can be written like

$$S(x) = 0, \quad (2.1.1)$$

where $S : \Omega \rightarrow B_2$ is a continuous operator in many cases using Mathematical Modelling [1, 7, 12, 13, 17, 19].

Solving such equations is a challenge. Closed form solutions x^* can be obtained only in some special cases. Therefore, researchers resort mostly to the utilization of iterative methods [1, 7, 12].

In the present chapter we shall approximate x^* with a very general iterative process allowing applications in diverse areas including right multivariate fractional calculus as follows: Let $A(\cdot) : \Omega \rightarrow \mathcal{L}(B_1, B_2)$ be a continuous operator and set

$$F = LS, \quad (2.1.2)$$

for some $L \in \mathcal{L}(B_2, B_1)$. The solution x^* is approximated as a limit of the sequence $\{x_n\}$ given for $x_0 \in \Omega$ by the fixed point scheme:

$$\begin{aligned} x_{n+1} &:= x_n + w_n, A(x_n) w_n + F(x_n) = 0 \\ \Leftrightarrow w_n &= Q(w_n) := (I - A(x_n)) w_n - F(x_n). \end{aligned} \quad (2.1.3)$$

Clearly, the sequence $\{x_n\}$ given by

$$x_{n+1} = Q(x_n) = Q^{(n+1)}(x_0) \quad (2.1.4)$$

is well defined. Suppose that sequence $\{x_n\}$ converges. Then, we can write:

$$Q^\infty(x_0) := \lim_{n \rightarrow \infty} (Q^n(x_0)) = \lim_{n \rightarrow \infty} x_n. \quad (2.1.5)$$

Many methods in the literature can be considered special cases of method (2.1.3). We can choose A to be: $A(x) = F'(x)$ (Newton's method), $A(x) = F'(x_0)$ (Modified Newton's method), $A(x) = [x, g(x); F]$, $g: \Omega \rightarrow B_1$ (Steffensen's method). Many other choices for A can be found in [1–21] and the references there in. Therefore, it is important to study the convergence of method (2.1.3) under generalized conditions. In particular, we present the semi-local convergence of method (2.1.3) using only continuity assumptions on operator F and for a so general operator A as to allow applications to right multivariate fractional calculus and other areas.

The rest of the chapter is organized as follows: Sect. 2.2 contains the semi-local convergence of method (2.1.3). In the concluding Sect. 2.3, we suggest some applications to right multivariate fractional calculus.

2.2 Convergence

Let $B(x, \xi)$, $\overline{B}(x, \xi)$ stand, respectively for the open and closed balls in B_1 with center $x \in B_1$ and of radius $\xi > 0$.

We present the semi-local convergence of method (2.1.3) in this section.

Theorem 2.1 *Let $F: \Omega \subset B_1 \rightarrow B_2$, $A(\cdot): \Omega \rightarrow \mathcal{L}(B_1, B_1)$ and $x_0 \in \Omega$ be as defined in the Introduction. Suppose: there exist $\delta_0 \in (0, 1)$, $\delta_1 \in (0, 1)$, $\eta \geq 0$ such that for each $x, y \in \Omega$*

$$\delta := \delta_0 + \delta_1 < 1, \quad (2.2.1)$$

$$\|F(x_0)\| \leq \eta, \quad (2.2.2)$$

$$\|I - A(x)\| \leq \delta_0, \quad (2.2.3)$$

$$\|F(y) - F(x) - A(x)(y - x)\| \leq \delta_1 \|y - x\| \quad (2.2.4)$$

and

$$\overline{B}(x_0, \delta) \subseteq \Omega, \quad (2.2.5)$$

where

$$\rho = \frac{\eta}{1 - \delta}. \quad (2.2.6)$$

Then, sequence $\{x_n\}$ generated for $x_0 \in \Omega$ by

$$x_{n+1} = x_n + Q_n^\infty(0), \quad Q_n(w) := (I - A(x_n))w - F(x_n) \quad (2.2.7)$$

is well defined in $\overline{B}(x_0, \rho)$, remains in $\overline{B}(x_0, \rho)$ for each $n = 0, 1, 2, \dots$ and converges to x^* which is the only solution of equation $F(x) = 0$ in $\overline{B}(x_0, \rho)$. Moreover, an apriori error estimate is given by the sequence $\{\rho_n\}$ defined by

$$\rho_0 := \rho, \quad \rho_n = T_n^\infty(0), \quad T_n(t) = \delta_0 + \delta_1 \rho_{n-1} \quad (2.2.8)$$

for each $n = 1, 2, \dots$ and satisfying

$$\lim_{n \rightarrow \infty} \rho_n = 0. \quad (2.2.9)$$

Furthermore, an aposteriori error estimate is given by the sequence $\{\sigma_n\}$ defined by

$$\sigma_n := H_n^\infty(0), \quad H_n(t) = \delta t + \delta_1 p_{n-1}, \quad (2.2.10)$$

$$q_n := \|x_n - x_0\| \leq \rho - \rho_n \leq \rho, \quad (2.2.11)$$

where

$$p_{n-1} := \|x_n - x_{n-1}\| \text{ for each } n = 1, 2, \dots \quad (2.2.12)$$

Proof We shall show using mathematical induction the following assertion is true:

(A_n) $x_n \in X$ and $\rho_n \geq 0$ are well defined and such that

$$\rho_n + p_{n-1} \leq \rho_{n-1}. \quad (2.2.13)$$

By the definition of ρ , (2.2.3)–(2.2.6) we have that there exists $r \leq \rho$ (Lemma 1.4 [7, pp.3]) such that

$$\delta_0 \tau + \|F(x_0)\| = r$$

and

$$\delta_0^k r \leq \delta_0^k \rho \rightarrow 0 \text{ as } k \rightarrow \infty.$$

That is (Lemma 1.5 [7, pp.4]) x_1 is well defined and $p_0 \leq r$.

We need the estimate:

$$T_1(\rho - r) = \delta_0(\rho - r) + \delta_1 \rho_0 =$$

$$\delta_0 \rho - \delta_0 r + \delta_1 \rho = G_0(\rho) - r = \rho - r.$$

That is (Lemma 1.4 [7, pp.3]) ρ_1 exists and satisfies

$$\rho_1 + p_0 \leq \rho - r + r = \rho = \rho_0.$$

Hence (I_0) is true. Suppose that for each $k = 1, 2, \dots, n$, assertion (I_k) is true. We must show: x_{k+1} exists and find a bound r for p_k . Indeed, we have in turn that

$$\begin{aligned} \delta_0 \rho_k + \delta_1 (\rho_{k-1} - \rho_k) &= \delta_0 \rho_k + \delta_1 \rho_{k-1} - \delta_1 \rho_k \\ &= T_k (\rho_k) - \delta_1 \rho_k \leq \rho_k. \end{aligned}$$

That is there exists $r \leq \rho_k$ such that

$$r = \delta_0 r + \delta_1 (\rho_{k-1} - \rho_k) \text{ and } (\delta_0 + \delta_1)^i r \rightarrow 0 \quad (2.2.14)$$

as $i \rightarrow \infty$.

The induction hypothesis gives that

$$q_k \leq \sum_{m=0}^{k-1} p_m \leq \sum_{m=0}^{k-1} (\rho_m - \rho_{m+1}) = \rho - \rho_k \leq \rho,$$

so $x_k \in \overline{B}(x_0, \rho) \subseteq \Omega$ and x_1 satisfies $\|I - A(x_1)\| \leq \delta_0$ (by (2.2.3)).

Using the induction hypothesis, (2.1.3) and (2.2.4), we get

$$\begin{aligned} \|F(x_k)\| &= \|F(x_k) - F(x_{k-1}) - A(x_{k-1})(x_k - x_{k-1})\| \\ &\leq \delta_1 p_{k-1} \leq \delta_1 (\rho_{k-1} - \rho_k) \end{aligned} \quad (2.2.15)$$

leading together with (2.2.14) to:

$$\delta_0 r + \|F(x_k)\| \leq r,$$

which implies x_{k+1} exists and $p_k \leq r \leq \rho_k$. It follows from the definition of ρ_{k+1} that

$$T_{k+1}(\rho_k - r) = T_k(\rho_k) - r = \rho_k - r,$$

so ρ_{k+1} exists and satisfies

$$\rho_{k+1} + p_k \leq \rho_k - r + r = \rho_k$$

so the induction for (I_n) is completed.

Let $j \geq k$. Then, we obtain in turn that

$$\|x_{j+k} - x_k\| \leq \sum_{i=k}^j p_i \leq \sum_{i=k}^j (\rho_j - \rho_{j+1}) = \rho_k - \rho_{j+k} \leq \rho_k. \quad (2.2.16)$$

We also get using induction that

$$\rho_{k+1} = T_{k+1}(\rho_{k+1}) \leq T_{k+1}(\rho_k) \leq \delta \rho_k \leq \dots \leq \delta^{k+1} \rho. \quad (2.2.17)$$

Hence, by (2.2.1) and (2.2.17) $\lim_{k \rightarrow \infty} \rho_k = 0$, so $\{x_k\}$ is a complete sequence in a Banach space X and as such it converges to some x^* . By letting $j \rightarrow \infty$ in (2.2.16), we conclude that $x^* \in \overline{B}(x_k, \rho_k)$. Moreover, by letting $k \rightarrow \infty$ in (2.2.15) and using the continuity of F we get that $F(x^*) = 0$. Notice that

$$H_k(\rho_k) \leq T_k(\rho_k) \leq \rho_k,$$

so the apriori bound exists. That is σ_k is smaller in general than ρ_k . Clearly, the conditions of the theorem are satisfied for x_k replacing x_0 (by (2.2.16)). Hence, by (2.2.8) $x^* \in \overline{B}(x_n, \sigma_n)$, which completes the proof for the aposteriori bound. ■

Remark 2.2 (a) It follows from the proof of Theorem 2.1 that the conclusions hold, if $A(\cdot)$ is replaced by a more general continuous operator $A : \Omega \rightarrow B_1$.

(b) In the next section some applications are suggested for special choices of the "A" operators with $\gamma_0 := \delta_0$ and $\gamma_1 := \delta_1$.

2.3 Applications to Right Multivariate Fractional Calculus

Our presented earlier semi-local convergence results, see Theorem 2.1, apply in the next two multivariate fractional settings given that the following inequalities are fulfilled:

$$\|1 - A(x)\|_\infty \leq \gamma_0 \in (0, 1), \quad (2.3.1)$$

and

$$\left\| (F(y) - F(x)) \vec{i} - A(x)(y - x) \right\| \leq \gamma_1 \|y - x\|, \quad (2.3.2)$$

where $\gamma_0, \gamma_1 \in (0, 1)$, furthermore

$$\gamma = \gamma_0 + \gamma_1 \in (0, 1), \quad (2.3.3)$$

for all $x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$, where $a_i < a_i^* < b_i^* < b_i, i = 1, \dots, k$.

Above \vec{i} is the unit vector in $\mathbb{R}^k, k \in \mathbb{N}, \|\vec{i}\| = 1$, and $\|\cdot\|$ is a norm in \mathbb{R}^k .

The specific functions $A(x)$, $F(x)$ will be described next.

(I) Consider the right multidimensional Riemann–Liouville fractional integral of order $\alpha = (\alpha_1, \dots, \alpha_k)$ ($\alpha_i > 0$, $i = 1, \dots, k$):

$$(I_{b-}^{\alpha} f)(x) = \frac{1}{\prod_{i=1}^k \Gamma(\alpha_i)} \int_{x_1}^{b_1} \dots \int_{x_k}^{b_k} \prod_{i=1}^k (t_i - x_i)^{\alpha_i-1} f(t_1, \dots, t_k) dt_1 \dots dt_k, \quad (2.3.4)$$

where Γ is the gamma function, $f \in L_{\infty} \left(\prod_{i=1}^k [a_i, b_i] \right)$, $b = (b_1, \dots, b_k)$, and

$$x = (x_1, \dots, x_k) \in \prod_{i=1}^k [a_i, b_i].$$

By [6], we get that $(I_{b-}^{\alpha} f)$ is a continuous function on $\prod_{i=1}^k [a_i, b_i]$. Furthermore by [6] we get that I_{b-}^{α} is a bounded linear operator, which is a positive operator, plus that $(I_{b-}^{\alpha} f)(b) = 0$.

In particular, $(I_{b-}^{\alpha} f)$ is continuous on $\prod_{i=1}^k [a_i^*, b_i^*]$.

Thus there exist $x_1, x_2 \in \prod_{i=1}^k [a_i^*, b_i^*]$ such that

$$\begin{aligned} (I_{b-}^{\alpha} f)(x_1) &= \min (I_{b-}^{\alpha} f)(x), \\ (I_{b-}^{\alpha} f)(x_2) &= \max (I_{b-}^{\alpha} f)(x), \end{aligned} \quad (2.3.5)$$

over all $x \in \prod_{i=1}^k [a_i^*, b_i^*]$.

We assume that

$$(I_{b-}^{\alpha} f)(x_1) > 0. \quad (2.3.6)$$

Hence

$$\|I_{b-}^{\alpha} f\|_{\infty, \prod_{i=1}^k [a_i^*, b_i^*]} = (I_{b-}^{\alpha} f)(x_2) > 0. \quad (2.3.7)$$

Here we define

$$Jf(x) = mf(x), \quad 0 < m < \frac{1}{2}, \quad (2.3.8)$$

for any $x \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Therefore the equation

$$Jf(x) = 0, \quad x \in \prod_{i=1}^k [a_i^*, b_i^*], \quad (2.3.9)$$

has the same solutions as the equation

$$F(x) := \frac{Jf(x)}{2(I_{b-}^\alpha f)(x_2)} = 0, \quad x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.10)$$

Notice that

$$I_{b-}^\alpha \left(\frac{f}{2(I_{b-}^\alpha f)(x_2)} \right)(x) = \frac{(I_{b-}^\alpha f)(x)}{2(I_{b-}^\alpha f)(x_2)} \leq \frac{1}{2} < 1, \quad x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.11)$$

Call

$$A(x) := \frac{(I_{b-}^\alpha f)(x)}{2(I_{b-}^\alpha f)(x_2)}, \quad \forall x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.12)$$

We notice that

$$0 < \frac{(I_{b-}^\alpha f)(x_1)}{2(I_{b-}^\alpha f)(x_2)} \leq A(x) \leq \frac{1}{2}, \quad \forall x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.13)$$

Hence the first condition (2.3.1) is fulfilled by

$$|1 - A(x)| = 1 - A(x) \leq 1 - \frac{(I_{b-}^\alpha f)(x_1)}{2(I_{b-}^\alpha f)(x_2)} =: \gamma_0, \quad \forall x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.14)$$

Hence $\|1 - A(x)\|_\infty \leq \gamma_0$, where $\|\cdot\|_\infty$ is over $\prod_{i=1}^k [a_i^*, b_i^*]$. Clearly $\gamma_0 \in (0, 1)$.

Next we assume that $\frac{f(x)}{2(I_{b-}^\alpha f)(x_2)}$ is a contraction, that is

$$\left| \frac{f(x)}{2(I_{b-}^\alpha f)(x_2)} - \frac{f(y)}{2(I_{b-}^\alpha f)(x_2)} \right| \leq \theta \|x - y\|, \quad \text{all } x, y \in \prod_{i=1}^k [a_i^*, b_i^*], \quad (2.3.15)$$

$$0 < \theta < 1.$$

Hence

$$\left| \frac{mf(x)}{2(I_{b-}^\alpha f)(x_2)} - \frac{mf(y)}{2(I_{b-}^\alpha f)(x_2)} \right| \leq m\theta \|x - y\| \leq \frac{\theta}{2} \|x - y\|, \quad (2.3.16)$$

all $x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Set $\lambda = \frac{\theta}{2}$, it is $0 < \lambda < \frac{1}{2}$. We have that

$$|F(x) - F(y)| \leq \lambda \|x - y\|, \quad (2.3.17)$$

all $x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Equivalently we have

$$|Jf(x) - Jf(y)| \leq 2\lambda (I_{b-}^\alpha f)(x_2) \|x - y\|, \quad \text{all } x, y \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.18)$$

We observe that

$$\begin{aligned} & \left\| (F(y) - F(x)) \overrightarrow{t} - A(x)(y - x) \right\| \leq \\ & |F(y) - F(x)| + |A(x)| \|y - x\| \leq \end{aligned} \quad (2.3.19)$$

$$\lambda \|y - x\| + |A(x)| \|y - x\| = (\lambda + |A(x)|) \|y - x\| =: (\psi_1),$$

$\forall x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

By [6], we have that

$$|(I_{b-}^\alpha f)(x)| \leq \left(\prod_{i=1}^k \frac{(b_i - a_i)^{\alpha_i}}{\Gamma(\alpha_i + 1)} \right) \|f\|_\infty, \quad (2.3.20)$$

$\forall x \in \prod_{i=1}^k [a_i^*, b_i^*]$, where $\|\cdot\|_\infty$ now is over $\prod_{i=1}^k [a_i, b_i]$.

Hence

$$|A(x)| = \frac{|(I_{b-}^\alpha f)(x)|}{2(I_{b-}^\alpha f)(x_2)} \leq \frac{1}{2(I_{b-}^\alpha f)(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{\alpha_i}}{\Gamma(\alpha_i + 1)} \right) \|f\|_\infty < \infty, \quad (2.3.21)$$

$\forall x \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Therefore we get

$$(\psi_1) \leq \left(\lambda + \frac{1}{2(I_{b-}^\alpha f)(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{\alpha_i}}{\Gamma(\alpha_i + 1)} \right) \|f\|_\infty \right) \|y - x\|, \quad (2.3.22)$$

$\forall x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Call

$$0 < \gamma_1 := \lambda + \frac{1}{2 (I_{b-}^{\alpha} f)(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{\alpha_i}}{\Gamma(\alpha_i + 1)} \right) \|f\|_{\infty}, \quad (2.3.23)$$

and by choosing $(b_i - a_i)$ small enough, $i = 1, \dots, k$, we can make $\gamma_1 \in (0, 1)$, fulfilling (2.3.2).

Next we call and we need that

$$0 < \gamma := \gamma_0 + \gamma_1 = \left(1 - \frac{(I_{b-}^{\alpha} f)(x_1)}{2 (I_{b-}^{\alpha} f)(x_2)} \right) + \left(\lambda + \frac{1}{2 (I_{b-}^{\alpha} f)(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{\alpha_i}}{\Gamma(\alpha_i + 1)} \right) \|f\|_{\infty} \right) < 1, \quad (2.3.24)$$

equivalently,

$$\lambda + \frac{1}{2 (I_{b-}^{\alpha} f)(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{\alpha_i}}{\Gamma(\alpha_i + 1)} \right) \|f\|_{\infty} < \frac{(I_{b-}^{\alpha} f)(x_1)}{2 (I_{b-}^{\alpha} f)(x_2)}, \quad (2.3.25)$$

equivalently,

$$2\lambda (I_{b-}^{\alpha} f)(x_2) + \left(\prod_{i=1}^k \frac{(b_i - a_i)^{\alpha_i}}{\Gamma(\alpha_i + 1)} \right) \|f\|_{\infty} < (I_{b-}^{\alpha} f)(x_1), \quad (2.3.26)$$

which is possible for small λ and small $(b_i - a_i)$, all $i = 1, \dots, k$. That is $\gamma \in (0, 1)$, fulfilling (2.3.3). So our numerical method converges and solves (2.3.9).

(II) Let $\alpha = (\alpha_1, \dots, \alpha_k)$, $\alpha_i > 0$, $m_i = \lceil \alpha_i \rceil$ ($\lceil \cdot \rceil$ ceiling function), $\alpha_i \notin \mathbb{N}$, $i = 1, \dots, k \in \mathbb{N}$, and $G \in C^{\sum_{i=1}^k m_i - 1} \left(\prod_{i=1}^k [a_i, b_i] \right)$, such that

$$0 \neq \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \in L_{\infty} \left(\prod_{i=1}^k [a_i, b_i] \right).$$

Here we consider the multivariate right Caputo type fractional mixed partial derivative of order α :

$$D_{b-}^{\alpha} G(x) = \frac{(-1)^{\sum_{i=1}^k m_i}}{\prod_{i=1}^k \Gamma(m_i - \alpha_i)} \int_{x_1}^{b_1} \dots \int_{x_k}^{b_k} \prod_{i=1}^k (t_i - x_i)^{m_i - \alpha_i - 1}. \quad (2.3.27)$$

$$\frac{\partial^{\sum_{i=1}^k m_i} G(t_1, \dots, t_k)}{\partial t_1^{m_1} \dots \partial t_k^{m_k}} dt_1 \dots dt_k,$$

where again Γ is the gamma function, $b = (b_1, \dots, b_k)$, $\forall x = (x_1, \dots, x_k) \in \prod_{i=1}^k [a_i, b_i]$. Notice here that $m_i - \alpha_i > 0$, $i = 1, \dots, k$.

By [6], we get that $D_{b-}^\alpha G$ is a continuous function on $\prod_{i=1}^k [a_i, b_i]$, and it holds that $D_{b-}^\alpha G(b) = 0$.

In particular $D_{b-}^\alpha G$ is continuous on $\prod_{i=1}^k [a_i^*, b_i^*]$, where $a_i < a_i^* < b_i^* < b_i$, $i = 1, \dots, k$.

Therefore there exist $x_1, x_2 \in \prod_{i=1}^k [a_i^*, b_i^*]$ such that

$$\begin{aligned} (D_{b-}^\alpha G)(x_1) &= \min (D_{b-}^\alpha G)(x), \\ (D_{b-}^\alpha G)(x_2) &= \max (D_{b-}^\alpha G)(x), \end{aligned} \quad (2.3.28)$$

over all $x \in \prod_{i=1}^k [a_i^*, b_i^*]$.

We assume that

$$(D_{b-}^\alpha G)(x_1) > 0. \quad (2.3.29)$$

Hence

$$\|D_{b-}^\alpha G\|_{\infty, \prod_{i=1}^k [a_i^*, b_i^*]} = (D_{b-}^\alpha G)(x_2) > 0. \quad (2.3.30)$$

Here we define

$$JG(x) = mG(x), \quad 0 < m < \frac{1}{2}, \quad (2.3.31)$$

for any $x \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Therefore the equation

$$JG(x) = 0, \quad x \in \prod_{i=1}^k [a_i^*, b_i^*], \quad (2.3.32)$$

has the same solutions as the equation

$$F(x) := \frac{JG(x)}{2D_{b-}^\alpha G(x_2)} = 0, \quad x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.33)$$

Notice that

$$D_{b-}^{\alpha} \left(\frac{G(x)}{2D_{b-}^{\alpha} G(x_2)} \right) = \frac{D_{b-}^{\alpha} G(x)}{2D_{b-}^{\alpha} G(x_2)} \leq \frac{1}{2} < 1, \quad x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.34)$$

We call

$$A(x) := \frac{D_{b-}^{\alpha} G(x)}{2D_{b-}^{\alpha} G(x_2)}, \quad \forall x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.35)$$

We notice that

$$0 < \frac{D_{b-}^{\alpha} G(x_1)}{2D_{b-}^{\alpha} G(x_2)} \leq A(x) \leq \frac{1}{2}. \quad (2.3.36)$$

Hence the first condition (2.3.1) is fulfilled by

$$|1 - A(x)| = 1 - A(x) \leq 1 - \frac{D_{b-}^{\alpha} G(x_1)}{2D_{b-}^{\alpha} G(x_2)} =: \gamma_0, \quad \forall x \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.37)$$

Hence

$$\|1 - A(x)\|_{\infty} \leq \gamma_0, \quad (2.3.38)$$

where $\|\cdot\|_{\infty}$ is over $\prod_{i=1}^k [a_i^*, b_i^*]$.

Clearly $\gamma_0 \in (0, 1)$.

Next we assume that $\frac{G(x)}{2(D_{b-}^{\alpha} G)(x_2)}$ is a contraction, that is

$$\left| \frac{G(x)}{2(D_{b-}^{\alpha} G)(x_2)} - \frac{G(y)}{2(D_{b-}^{\alpha} G)(x_2)} \right| \leq \theta \|x - y\|, \quad \text{all } x, y \in \prod_{i=1}^k [a_i^*, b_i^*], \quad (2.3.39)$$

with $0 < \theta < 1$.

Hence

$$\left| \frac{mG(x)}{2(D_{b-}^{\alpha} G)(x_2)} - \frac{mG(y)}{2(D_{b-}^{\alpha} G)(x_2)} \right| \leq m\theta \|x - y\| \leq \frac{\theta}{2} \|x - y\|, \quad (2.3.40)$$

all $x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Set $\lambda = \frac{\theta}{2}$, it is $0 < \lambda < \frac{1}{2}$. We have that

$$|F(x) - F(y)| \leq \lambda \|x - y\|, \quad (2.3.41)$$

all $x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Equivalently we have

$$|JG(x) - JG(y)| \leq 2\lambda (D_{b-}^\alpha G)(x_2) \|x - y\|, \quad \text{all } x, y \in \prod_{i=1}^k [a_i^*, b_i^*]. \quad (2.3.42)$$

We observe that

$$\begin{aligned} & \left\| (F(y) - F(x)) \vec{t} - A(x)(y - x) \right\| \leq \\ & |F(y) - F(x)| + |A(x)| \|y - x\| \leq \\ & \lambda \|y - x\| + |A(x)| \|y - x\| = (\lambda + |A(x)|) \|y - x\| =: (\psi_2), \end{aligned} \quad (2.3.43)$$

$\forall x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

By (2.3.27), we notice that

$$\begin{aligned} |D_{b-}^\alpha G(x)| & \leq \frac{1}{\prod_{i=1}^k \Gamma(m_i - \alpha_i)}. \\ & \left(\int_{x_1}^{b_1} \dots \int_{x_k}^{b_k} \prod_{i=1}^k (t_i - x_i)^{m_i - \alpha_i - 1} dt_1 \dots dt_k \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty \\ & = \frac{1}{\prod_{i=1}^k \Gamma(m_i - \alpha_i)} \left(\prod_{i=1}^k \frac{(b_i - x_i)^{m_i - \alpha_i}}{m_i - \alpha_i} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty \\ & = \left(\prod_{i=1}^k \frac{(b_i - x_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty. \end{aligned} \quad (2.3.44)$$

We have proved that

$$|D_{b-}^\alpha G(x)| \leq \left(\prod_{i=1}^k \frac{(b_i - a_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty, \quad (2.3.45)$$

$\forall x \in \prod_{i=1}^k [a_i^*, b_i^*]$, where $\|\cdot\|_\infty$ now is over $\prod_{i=1}^k [a_i, b_i]$.

Hence we get

$$|A(x)| \leq \frac{1}{2D_{b-}^\alpha G(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty < \infty, \quad (2.3.46)$$

$\forall x \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Therefore we obtain

$$(\psi_2) \leq \left(\lambda + \frac{1}{2D_{b-}^\alpha G(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty \right) \|y - x\|, \quad (2.3.47)$$

$\forall x, y \in \prod_{i=1}^k [a_i^*, b_i^*]$.

Call

$$0 < \gamma_1 := \lambda + \frac{1}{2D_{b-}^\alpha G(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty, \quad (2.3.48)$$

and by choosing $(b_i - a_i)$ small enough, $i = 1, \dots, k$, we can make $\gamma_1 \in (0, 1)$, fulfilling (2.3.2).

Next we call and we need that

$$0 < \gamma := \gamma_0 + \gamma_1 = \left(1 - \frac{D_{b-}^\alpha G(x_1)}{2D_{b-}^\alpha G(x_2)} \right) + \left\{ \lambda + \frac{1}{2D_{b-}^\alpha G(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty \right\} < 1, \quad (2.3.49)$$

equivalently,

$$\lambda + \frac{1}{2D_{b-}^\alpha G(x_2)} \left(\prod_{i=1}^k \frac{(b_i - a_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\partial^{\sum_{i=1}^k m_i} G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_\infty < \frac{D_{b-}^\alpha G(x_1)}{2D_{b-}^\alpha G(x_2)}, \quad (2.3.50)$$

equivalently,

$$2\lambda D_{b-}^{\alpha} G(x_2) + \left(\prod_{i=1}^k \frac{(b_i - a_i)^{m_i - \alpha_i}}{\Gamma(m_i - \alpha_i + 1)} \right) \left\| \frac{\sum_{i=1}^k m_i G}{\partial x_1^{m_1} \dots \partial x_k^{m_k}} \right\|_{\infty} < D_{b-}^{\alpha} G(x_1), \quad (2.3.51)$$

which is possible for small λ and small $(b_i - a_i)$, all $i = 1, \dots, k$. That is $\gamma \in (0, 1)$, fulfilling (2.3.3). So our numerical method converges and solves (2.3.32).

References

1. S. Amat, S. Busquier, S. Plaza, Chaotic dynamics of a third-order Newton-type method. *J. Math. Anal. Appl.* **366**(1), 164–174 (2010)
2. G. Anastassiou, *Fractional Differentiation Inequalities* (Springer, New York, 2009)
3. G. Anastassiou, Fractional representation formulae and right fractional inequalities. *Math. Comput. Model.* **54**(10–12), 3098–3115 (2011)
4. G. Anastassiou, *Intelligent Mathematics: Computational Analysis* (Springer, Heidelberg, 2011)
5. G. Anastassiou, *Advanced Inequalities* (World Scientific Publ. Corp, Singapore, 2011)
6. G. Anastassiou, On right multidimensional Riemann-Liouville fractional integral. *J. Comput. Anal. Appl.* (2015)
7. G. Anastassiou, I.K. Argyros, *Intelligent Numerical Methods: Applications to Fractional Calculus*, Studies in Computational Intelligence (Springer, Heidelberg, 2016)
8. G. Anastassiou, I. Argyros, Fixed point schemes with applications in right multivariate fractional calculus. submitted for publication (2015)
9. I.K. Argyros, A unifying local-semilocal convergence analysis and applications for two-point Newton-like methods in Banach space. *J. Math. Anal. Appl.* **298**, 374–397 (2004)
10. I.K. Argyros, *Convergence and Applications of NewtonType Iterations* (Springer, New York, 2008)
11. I.K. Argyros, On a class of Newton-like methods for solving nonlinear equations. *J. Comput. Appl. Math.* **228**, 115–122 (2009)
12. I.K. Argyros, A semilocal convergence analysis for directional Newton methods. *AMS J.* **80**, 327–343 (2011)
13. I.K. Argyros, Y.J. Cho, S. Hilout, *Numerical Methods for Equations and Its Applications* (CRC Press/Taylor and Francis, New York, 2012)
14. I.K. Argyros, S. Hilout, Weaker conditions for the convergence of Newton's method. *J. Complex.* **28**, 364–387 (2012)
15. J.A. Ezquerro, J.M. Gutiérrez, M.A. Hernández, N. Romero, M.J. Rubio, The Newton method: from Newton to Kantorovich (Spanish). *Gac. R. Soc. Mat. Esp.* **13**, 53–76 (2010)
16. J.A. Ezquerro, M.A. Hernández, Newton-type methods of high order and domains of semilocal and global convergence. *Appl. Math. Comput.* **214**(1), 142–154 (2009)
17. L.V. Kantorovich, G.P. Akilov, *Functional Analysis in Normed Spaces* (Pergamon Press, New York, 1964)
18. A.A. Magreñán, Different anomalies in a Jarratt family of iterative root finding methods. *Appl. Math. Comput.* **233**, 29–38 (2014)
19. A.A. Magreñán, A new tool to study real dynamics: the convergence plane. *Appl. Math. Comput.* **248**, 215–224 (2014)
20. F.A. Potra, V. Ptak, *Nondiscrete Induction and Iterative Processes* (Pitman, London, 1984)
21. P.D. Proinov, New general convergence theory for iterative processes and its applications to Newton-Kantorovich type theorems. *J. Complex.* **26**, 3–42 (2010)

Intelligent Numerical Methods II: Applications to
Multivariate Fractional Calculus

Anastassiou, G.A.; Argyros, I.K.

2016, XII, 116 p., Hardcover

ISBN: 978-3-319-33605-3