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% C. Petersen, H. Werkle, Dynamik der Baukonstruktionen
% 2. Auflage, Springer Vieweg, Wiesbaden, 2018
%
% ML_05_3_Uebertragungsverfahren: Übertragungsverfahren
%
% Version 1.0, April 2018
% Softwareentwicklung:
% Andrei Firus, M.Eng (andrei.firus@gmail.com)

% Aufbau Eingabedatei:
%   - Spalte 1: Zeitvektor des Kraftverlaufs [s]
%   - Spalte 2: Kraftvektor [N]
% ANMERKUNG: Dezimaltrennzeichen '.'

% Ausgabedateien:
% Outputdatei_1: Eingaben- und Ergebnisübersicht
% Outputdatei_2: Verschiebungszeitverlauf
% Outputdatei_3: Geschwindigkeitszeitverlauf
% Outputdatei_4: Verlauf der am Fußpunkt abgesetzten Kraft

%----- EINGABEBLOCK -----
m=1000;           % Masse [kg]
k=25000;          % Federkonstante [N/m]
xi=0.02;          % Dämpfungsmaß [-]

na=200;           % Anzahl der Intervalle für den
                  % Ausschwingvorgang (ganze Zahl)

Ta=0.1;           % Breite der Zeitintervalle im
                  % Ausschwingvorgang [s]

y_0=0;            % Anfangswert der Verschiebung zum
                  % Zeitpunkt 0 [m]

v_0=0;            % Anfangswert der Geschwindigkeit zum
                  % Zeitpunkt 0 [m/s]

%-----
% Einlesen des Kraftzeitverlaufs von der Eingabedatei und Generierung der
% entsprechenden Vektoren
Zeitverlauf=dlmread('Inputdatei_1.txt');
t_kraft=Zeitverlauf(:,1);
Kraft=Zeitverlauf(:,2);
%-----

%----- BERECHNUNGSBLOCK -----
% Berechnung weiterer System- und Berechnungsparameter
omega=sqrt(k/m);   % Eigenkreisfrequenz
f=omega/(2*pi);    % Eigenfrequenz
T=1/f;             % Eigenschwingzeit
d=xi*(2*omega*m);  % Dämpfungskoeffizient
omega_d=sqrt(1-xi^2)*omega; % gedämpfte Eigenkreisfrequenz

n=length(Kraft)-1; % Anzahl der Zeitintervalle innerhalb derer
                  % die Last einwirkt

Tf=zeros(n,1);     % Breite des Zeitintervalle: Einwirkung

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for i=1:1:n
    Tf(i)=t_kraft(i+1)-t_kraft(i);
end

nn=n+na; % Gesamtanzahl der Intervalle, für die die
          % Schwingreaktion berechnet werden soll

% Steigung der Geraden in jedem Intervall
p=zeros(n,1);
for i=1:1:n
    p(i)=(Kraft(i+1)-Kraft(i))/(Tf(i));
end

% Berechnung der Schwingungsantwort mit dem Übertragungsverfahren
ts=zeros(nn,1);
y=zeros(nn,1);
v=zeros(nn,1);
fb=zeros(nn,1);

% Definition der endgültigen Ergebnisvektoren
y_f=zeros(nn+1,1);
y_f(1)=y_0;
v_f=zeros(nn+1,1);
v_f(1)=v_0;
fb_f=zeros(nn+1,1);
fb_f(1)=v_0*d+y_0*k;

% Anfangswerte für die Berechnung
y0=y_0;
v0=v_0;

% Zeitvektoren für die Berechnung
ts(1)=Tf(1);
for i=1:1:n-1
    ts(i+1)=ts(i)+Tf(i+1);
end
for i=n:1:nn-1
    ts(i+1)=ts(i)+Ta;
end

% Berechnungsvorschrift für die Lasteinwirkungszeit
for i=1:1:n
    t=Tf(i);

    % Hilfswerte
    z1=exp(-xi*omega*t);
    z2=sin(omega_d*t);
    z3=cos(omega_d*t);
    z4=p(i);
    z5=Kraft(i);
    z6=z5-(d*z4/k);
    z7=z4+xi*omega*z6;

    a=xi*omega*y0/omega_d+(v0/omega_d)-(z7/(k*omega_d));
    b=y0-(z6/k);

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y(i)=(z1*(a*z2+b*z3))+((z6+z4*t)/k);
v(i)=z1*(omega_d*(a*z3-b*z2)-xi*omega*(a*z2+b*z3))+z4/k;
fb(i)=d*v(i)+k*y(i);

y0=y(i);
v0=v(i);
end
% Berechnungsvorschrift für den Ausschwingvorgang
for i=n+1:1:nn
    t=Ta;

    z1=exp(-xi*omega*t);
    z2=sin(omega_d*t);
    z3=cos(omega_d*t);

    a=xi*omega*y0/omega_d+v0/omega_d;
    b=y0;

    y(i)=z1*(a*z2+b*z3);
    v(i)=z1*(omega_d*(a*z3-b*z2)-xi*omega*(a*z2+b*z3));
    fb(i)=d*v(i)+k*y(i);

    y0=y(i);
    v0=v(i);
end
for i=1:1:nn
    y_f(i+1)=y(i);
    v_f(i+1)=v(i);
    fb_f(i+1)=fb(i);
end

% Extremwerte
ymax=max(y_f);    ymin=min(y_f);
vmax=max(v_f);    vmin=min(v_f);
fbmax=max(fb_f);  fbmin=min(fb_f);
%-----

%----- DARSTELLUNGSBLOCK -----
%Grafische Darstellung der Ergebnisse
name_fig1 = 'Zeitverläufe';
fig1=figure('Name',name_fig1,'NumberTitle','off');
set(fig1,'Position',[1000 50 700 900]);
Zeit_plot=zeros(length(y_f),1);
Zeit_plot(1)=0;
for i=2:1:length(y_f)
    Zeit_plot(i)=ts(i-1);
end
Kraft_plot=zeros(length(y_f),1);
for i=1:1:length(y_f)
    if i<=length(Kraft)
        Kraft_plot(i)=Kraft(i);
    else
        Kraft_plot(i)=0;
    end
end
end

subplot(4,1,1)

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plot(Zeit_plot,Kraft_plot,'r','LineWidth', 1);
title('Kraftzeitverlauf');
xlabel('Zeit [s]');
ylabel('Kraft [N]');
grid on;

subplot(4,1,2)
plot(Zeit_plot,y_f,'b','LineWidth', 1);
title('Verschiebungszeitverlauf');
xlabel('Zeit [s]');
ylabel('Verschiebung [m]');
grid on;

subplot(4,1,3)
plot(Zeit_plot,v_f,'b','LineWidth', 1);
title('Geschwindigkeitszeitverlauf');
xlabel('Zeit [s]');
ylabel('Geschwindigkeit [m/s]');
grid on;

subplot(4,1,4)
plot(Zeit_plot,fb_f,'b','LineWidth', 1);
title('Kraft am Fußpunkt');
xlabel('Zeit [s]');
ylabel('Kraft [N]');
grid on;
%-----

%----- AUSGABEBLOCK -----
% Ausgabe der Ergebnisse in eine Datei
fid = fopen('Outputdatei_1_Allgemein.txt', 'w');
fprintf(fid,...
    '%s\n','C. Petersen, H. Werkle, Dynamik der Baukonstruktionen');
fprintf(fid,...
    '%s\n','2. Auflage, Springer Vieweg, Wiesbaden, 2018');
fprintf(fid,...
    '%s\n','Softwareentwicklung: Andrei Firus (andrei.firus@gmail.com)');
fprintf(fid,'%s\n','Programm ML_05_3: Eingaben- und Ergebnisuebersicht');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,...
    '%s\n','-----');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,...
    '%s\n','EINGABEDATEN:');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Masse des Einfreiheitsgradschwingers [kg]:');
fprintf(fid,'%d\n',m);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Federkonstante [N/m]:');
fprintf(fid,'%d\n',k);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Daempfungsmass [-]:');

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fprintf(fid, '%s\n', 'Maximale Verschiebung [m]:');  
fprintf(fid, '%d\n', ymax);  
fprintf(fid, '%s\n', ' ');  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fprintf(fid, '%s\n', 'Minimale Verschiebung [m]:');  
fprintf(fid, '%d\n', ymin);  
fprintf(fid, '%s\n', ' ');  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fprintf(fid, '%s\n', 'Maximale Geschwindigkeit [m/s]:');  
fprintf(fid, '%d\n', vmax);  
fprintf(fid, '%s\n', ' ');  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fprintf(fid, '%s\n', 'Minimale Geschwindigkeit [m/s]:');  
fprintf(fid, '%d\n', vmin);  
fprintf(fid, '%s\n', ' ');  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fprintf(fid, '%s\n', 'Maximale Kraft am Fusspunkt [N]:');  
fprintf(fid, '%d\n', fbmax);  
fprintf(fid, '%s\n', ' ');  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fprintf(fid, '%s\n', 'Minimale Kraft am Fusspunkt [N]:');  
fprintf(fid, '%d\n', fbmin);  
fprintf(fid, '%s\n', ' ');  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fprintf(fid, ...  
    '%s\n', '-----');  
fprintf(fid, '%s\n', ' ');  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fprintf(fid, '%s\n', 'Kraftzeitverlauf:');  
fprintf(fid, '%s \t %s\n', 'Zeit [s]', 'Kraft [N]');  
for ii=1:length(Kraft)  
    fprintf(fid, '%d \t %d\n', t_kraft(ii), Kraft(ii));  
end  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
fclose(fid);  
  
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%  
Ergebnis_Verschiebungen=[Zeit_plot y_f];  
fid = fopen('Outputdatei_2_Verschiebungen.txt', 'w');  
fprintf(fid, ...  
    '%s\n', 'C. Petersen, H. Werkle, Dynamik der Baukonstruktionen');  
fprintf(fid, ...  
    '%s\n', '2. Auflage, Springer Vieweg, Wiesbaden, 2018');  
fprintf(fid, ...  
    '%s\n', 'Softwareentwicklung: Andrei Firus (andrei.firus@gmail.com)');  
fprintf(fid, '%s\n', 'Programm ML_05_3: Verschiebungszeitverlauf');  
fprintf(fid, '%s\n', ' ');  
fprintf(fid, ...  
    '%s\n', '-----');  
fprintf(fid, '%s\n', ' ');  
fprintf(fid, '%s\n', 'Verschiebungszeitverlauf:');  
fprintf(fid, '%s \t %s\n', 'Zeit [s]', 'Verschiebung [m]');  
for ii=1:length(y_f)  
    fprintf(fid, '%d \t %d\n', Ergebnis_Verschiebungen(ii,:));  
end  
fclose(fid);
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[illegible]