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% C. Petersen, H. Werkle, Dynamik der Baukonstruktionen
% 2. Auflage, Springer Vieweg, Wiesbaden, 2018
%
% ML_06_2_Freie_Schwingungen_eines_EFS_mit_Coulombscher_Reibung:
% Freie Schwingungen eines Einfreiheitsgradschwingers mit Coulombscher
% Reibung
%
% Version 1.0, April 2018
% Softwareentwicklung:
% Andrei Firus, M.Eng (andrei.firus@gmail.com)

% Aufbau Eingabedatei: Eingabedatei nicht notwendig

% Ausgabedateien:
% Outputdatei_1: Eingaben- und Ergebnisübersicht
% Outputdatei_2: Verschiebungszeitverlauf [m]
% Outputdatei_3: Geschwindigkeitszeitverlauf [m/s]
% Outputdatei_4: Beschleunigungszeitverlauf [m/s^2]
%----- EINGABEBLOCK -----
m=100; % Masse des EFS [kg]
k=10000; % Federkonstante [N/m]

r=100; % Reibungskraft [N]

y0=0.125; % Anfangsauslenkung [m]
v0=0; % Anfangsgeschwindigkeit [m/s]

n_dt=40; % Anzahl der Unterteilungen von der
          % Eigenschwingzeit für die Festlegung des
          % Berechnungszeitschrittes [-]

t_ber=15; % Gesamtzeit der Berechnung [s]
%-----

%----- BERECHNUNGSBLOCK -----
omega=sqrt(k/m); % Eigenkreisfrequenz
f=omega/(2*pi); % Eigenfrequenz
T=1/f; % Eigenschwingzeit
dt=T/n_dt; % Zeitschritt
d_tau=dt/T; % Berechnungszeitschritt (bezogene Zeit)
nt=ceil(t_ber/dt); % Anzahl Berechnungszeitschritte
tau_b=0:d_tau:t_ber/T; % Bezogener Zeitvektor für die Berechnung
t_b=0:dt:t_ber; % Zeitvektor für die Berechnung
%-----

% Berechnung der Schwingungsantwort mittels Differenzenverfahren
y=zeros(nt,1); % Definition des Verschiebungsvektors
v=zeros(nt,1); % Definition des Geschwindigkeitsvektors
a=zeros(nt,1); % Definition des Beschleunigungsvektors
y(1)=y0;
v(1)=v0;
y(2)=(1-2*pi^2*(d_tau)^2)*y(1)+v(1)*d_tau-((2*pi^2)/k)*sign(v(1))*r*...
    d_tau^2;
v(2)=(1/(2*dt))*(4*y(2)-4*y0-2*v0*dt);

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% Berechnung der Verschiebungen und Geschwindigkeiten
for i=3:1:nt
    y(i)=2*(1-2*pi^2*(d_tau)^2)*y(i-1)-y(i-2)-...
    sign(v(i-1))*r*((2*pi)^2/k)*d_tau^2;

    v(i)=(1/(2*dt))*(3*y(i)-4*(y(i-1))+y(i-2));

    if (sign(v(i))~=sign(v(i-1))) && (abs(y(i))<=r/k)
        nm=i; break % nm: Zeitschritt bei Erreichung des Stillstandes
    end
end

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% Vektoren bis zum Stillstand (Federkraft kleiner als die Reibungskraft)
tau_nm=tau_b(1:nm);
t_nm=t_b(1:nm);
y_nm=y(1:nm);
v_nm=v(1:nm);

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% Berechnung der Beschleunigungen
a(1)=(-k*y(1)-sign(v(1))*r)/m;
for i=2:1:nm-1
    a(i)=(1/dt^2)*(y(i+1)-2*y(i)+y(i-1));
end
a_nm=a(1:nm);
%-----

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%----- DARSTELLUNGSBLOCK -----

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%Grafische Darstellung der Ergebnisse
name_fig1 = 'Zeitverläufe';
fig1=figure('Name',name_fig1,'NumberTitle','off');
set(fig1,'Position',[1000 50 700 900]);

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subplot(3,1,1)
% Definition der Geraden (positiv und negativ)
if y0>=0
    [pks,locs]=findpeaks(y);
else
    [pks,locs]=findpeaks(-y);
end
g=zeros(length(pks)+1,1);
g(1)=abs(y0);
for i=2:1:length(g)
    g(i)=pks(i-1);
end
t_fig=[0 tau_nm(locs-1)];
plot(tau_nm,y_nm);
hold on;
plot(t_fig,g,'-.r',t_fig,-g,'-.r','MarkerSize',3);
title('Verschiebungszeitverlauf');
xlabel('bezogene Zeit [-]');
ylabel('Verschiebung [m]');
grid on; zoom on;

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subplot(3,1,2)
plot(tau_nm,v_nm,'MarkerSize',3);
title('Geschwindigkeitszeitverlauf');
xlabel('bezogene Zeit [-]');

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ylabel('Geschwindigkeit [m/s]');
grid on; zoom on;

subplot(3,1,3)
plot(tau_nm,a_nm,'MarkerSize',3);
title('Beschleunigungszeitverlauf');
xlabel('bezogene Zeit [-]');
ylabel('Beschleunigung [m/s^2]');
grid on; zoom on;
%-----

%----- AUSGABEBLOCK -----
% Ausgabe der Ergebnisse in eine Datei
fid = fopen('Outputdatei_1_Allgemein.txt', 'w');
fprintf(fid,...
    '%s\n','C. Petersen, H. Werkle, Dynamik der Baukonstruktionen');
fprintf(fid,...
    '%s\n','2. Auflage, Springer Vieweg, Wiesbaden, 2018');
fprintf(fid,...
    '%s\n','Softwareentwicklung: Andrei Firus (andrei.firus@gmail.com)');
fprintf(fid,'%s\n','Programm ML_06_2: Eingaben- und Ergebnisuebersicht');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,...
    '%s\n','-----');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,...
    '%s\n','EINGABEDATEN:');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Masse des Einfreiheitsgradschwingers [kg]:');
fprintf(fid,'%d\n',m);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Federkonstante [N/m]:');
fprintf(fid,'%d\n',k);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Reibungskraft [N]:');
fprintf(fid,'%d\n',r);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Anfangsauslenkung [m]:');
fprintf(fid,'%d\n',y0);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Anfangsgeschwindigkeit [m/s]:');
fprintf(fid,'%d\n',v0);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s %s\n%s\n','Anzahl der Unterteilungen der',...
    'Eigenschwingzeit für','den Berechnungszeitschritt [-]:');
fprintf(fid,'%d\n',n_dt);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid,'%s\n','Gesamtzeit der Berechnung [s]:');
fprintf(fid,'%d\n',t_ber);

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fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, ...
        '%s\n', '-----');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, ...
        '%s\n', 'ERGEBNISSE:');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Eigenkreisfrequenz [1/s]:');
fprintf(fid, '%d\n', omega);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Eigenfrequenz [Hz]:');
fprintf(fid, '%d\n', f);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Eigenschwingzeit [s]:');
fprintf(fid, '%d\n', T);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Zeitschritt [s]:');
fprintf(fid, '%d\n', dt);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Auf die Eigenschwingzeit bezogener Zeitschritt [-]:');
fprintf(fid, '%d\n', d_tau);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Anzahl der Berechnungszeitschritte [-]:');
fprintf(fid, '%d\n', nt);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Berechnungszeitschritte bis zum Stillstand [-]:');
fprintf(fid, '%d\n', nm);
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, '%s\n', 'Endamplitude [m]:');
fprintf(fid, '%d\n', y(nm));
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fprintf(fid, ...
        '%s\n', '-----');
fprintf(fid, '%s\n', ' ');
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
fclose(fid);

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
Ergebnis_Verschiebungen=[tau_nm' y_nm];
fid = fopen('Outputdatei_2_Verschiebungen.txt', 'w');
fprintf(fid, ...
        '%s\n', 'C. Petersen, H. Werkle, Dynamik der Baukonstruktionen');
fprintf(fid, ...
        '%s\n', '2. Auflage, Springer Vieweg, Wiesbaden, 2018');
fprintf(fid, ...
        '%s\n', 'Softwareentwicklung: Andrei Firus (andrei.firus@gmail.com)');
fprintf(fid, '%s\n', 'Programm ML_06_2: Verschiebungszeitverlauf');

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[illegible]