

Contents

Mass Equivalent Pantographs for Synthesis of Balanced Focal Mechanisms	1
Volkert van der Wijk	
Compliant Serial 3R Chain with Spherical Flexures	11
Farid Parvari Rad, Rocco Vertechy, Giovanni Berselli and Vincenzo Parenti-Castelli	
Combining Tube Design and Simple Kinematic Strategy for Follow-the-Leader Deployment of Concentric Tube Robots	23
Cédric Girerd, Kanty Rabenoroosa and Pierre Renaud	
A Screw-Based Dynamic Balancing Approach, Applied to a 5-Bar Mechanism	33
Jan de Jong, Johannes van Dijk and Just Herder	
A Novel S-C-U Dual Four-Bar Linkage	43
Pierre Larochelle and Sida Du	
Inverse Kinematics Analysis of a P2CuP2Cu Concentric Tube Robot with Embedded Micro-actuation for 3T-1R Contactless Tasks	51
Mohamed Taha Chikhaoui, Kanty Rabenoroosa and Nicolas Andreff	
Structural Synthesis of Hands for Grasping and Manipulation Tasks	61
Ali Tamimi, Alba Perez-Gracia and Martin Pucheta	
Generalized Construction of Bundle-Folding Linkages	71
Shengnan Lu, Dimiter Zlatanov, Matteo Zoppi and Xilun Ding	
A Complete Analysis of Singularities of a Parallel Medical Robot	81
Josef Schadlbauer, Calin Vaida, Paul Tucan, Doina Pislă, Manfred Husty and Nicolae Plitea	

Workspace Analysis of a 3-PSP Motion Platform	91
Luc Baron	
Posture Optimization of a Functionally Redundant Parallel Robot	101
David Corinaldi, Jorge Angeles and Massimo Callegari	
Analysis Methods for the 3-RRR with Uncertainties in the Design Parameters	109
Joshua K. Pickard, Juan A. Carretero and Jean-Pierre Merlet	
A Study on Simplified Dynamic Modeling Approaches of Delta Parallel Robots	119
Jan Brinker, Philipp Ingenlath and Burkhard Corves	
Hidden Cusps	129
Michel Coste, Philippe Wenger and Damien Chablat	
Some Mobile Overconstrained Parallel Mechanisms	139
J.M. Selig	
On the Line-Symmetry of Self-motions of Linear Pentapods	149
Georg Nawratil	
On Some Notable Singularities of 3-RPR and 3- RRR PPRMs	161
Khaled Assad Arrouk, Belhassen Chedli Bouzgarrou and Grigore Gogu	
Minimized-Torque-Oriented Design of Parallel Modular Mechanism for Humanoid Waist	171
Mouna Souissi, Vincent Hugel, Samir Garbaya and John Nassour	
Kinematic Analysis of the Delthaptic, a New 6-DOF Haptic Device	181
Margot Vulliez, Said Zeghloul and Oussama Khatib	
A Family of Non-overconstrained 3-DoF Reconfigurable Parallel Manipulators	191
Matteo-Claudio Palpacelli, Luca Carbonari, Giacomo Palmieri and Massimo Callegari	
Dealing with Redundancy of a Multiple Mobile Coil Magnetic Manipulator: A 3RPR Magnetic Parallel Kinematics Manipulator	201
Baptiste Véron, Arnaud Hubert, Joel Abadie and Nicolas Andreff	
A New Generic Approach for the Inverse Kinematics of Cable-Driven Parallel Robot with 6 Deformable Cables	209
Jean-Pierre Merlet	
Rolling Contact in Kinematics of Multifingered Robotic Hands	217
Lei Cui and Jian S. Dai	

Synergies Evaluation of the SCHUNK S5FH for Grasping Control	225
Fanny Ficuciello, Alba Federico, Vincenzo Lippiello and Bruno Siciliano	
In-Hand Manipulative Synthesis Using Velocity Subspaces	235
Neda Hassanzadeh, Shramana Ghosh and Nina Robson	
Synthesis of Linkages to Trace Plane Curves	245
Yang Liu and J. Michael McCarthy	
Subject-Specific Model of Knee Natural Motion: A Non-invasive Approach	255
Michele Conconi, Nicola Sancisi and Vincenzo Parenti-Castelli	
An Approach for Bone Pose Estimation via Three External Ellipsoid Pressure Points	265
Nikolas Bufe, Ansgar Heinemann, Peter Köhler and Andrés Kecskeméthy	
Robot Dynamics Constraint for Inverse Kinematics	275
Enrico Mingo Hoffman, Alessio Rocchi, Nikos G. Tsagarakis and Darwin G. Caldwell	
Path Planning in Kinematic Image Space Without the Study Condition	285
Martin Pfurner, Hans-Peter Schröcker and Manfred Husty	
The 2D Orientation Interpolation Problem: A Symmetric Space Approach	293
Yuanqing Wu, Andreas Müller and Marco Carricato	
Closure Polynomials for Strips of Tetrahedra	303
Federico Thomas and Josep M. Porta	
Robust Design of Parameter Identification	313
Aurélien Massein, David Daney and Yves Papegay	
Isotropic Design of the Spherical Wrist of a Cable-Driven Parallel Robot	321
Angelos Platis, Tahir Rasheed, Philippe Cardou and Stéphane Caro	
Dynamic Recovery of Cable-Suspended Parallel Robots After a Cable Failure	331
Alessandro Berti, Marc Gouttefarde and Marco Carricato	
Workspace and Interference Analysis of Cable-Driven Parallel Robots with an Unlimited Rotation Axis	341
Andreas Pott and Philipp Miermeister	
Elasto-Static Model for Point Mass Sagged Cable-Suspended Robots	351
Erika Ottaviano, Vincenzo Gattulli and Francesco Potenza	

Determination of a Dynamic Feasible Workspace for Cable-Driven Parallel Robots	361
Lorenzo Gagliardini, Marc Gouttefarde and Stephane Caro	
Adaptive Human Robot Cooperation Scheme for Bimanual Robots.	371
Bojan Nemec, Nejc Likar, Andrej Gams and Aleš Ude	
Influence of the Wind Load in the Trolley-Payload System with a Flexible Hoist Rope	381
Jianjie Zhang and Gabriel Abba	
Towards a Unified Notion of Kinematic Singularities for Robot Arms and Non-holonomic Platforms	393
Andreas Müller and Peter Donelan	
Dynamic Singularities of Non-holonomic Robotic Systems: An Analytic Approach	403
Krzysztof Tchoń	
A Taylor-Based Continuation Method for the Determination and Classification of Robot Singularities.	413
Gauthier Hentz, Isabelle Charpentier, Lennart Rubbert and Pierre Renaud	
Identifying Singularity-Free Spheres in the Position Workspace of Semi-regular Stewart Platform Manipulators.	421
Anirban Nag, Vikranth Reddy, Saurav Agarwal and Sandipan Bandyopadhyay	
Geometric Algebra Based Kinematics Model and Singularity of a Hybrid Surgical Robot	431
Tanio K. Tanev	
Kinematic Singularities of a 3-DoF Planar Geared Robot Manipulator.	441
S. Vahid Amirinezhad and Peter Donelan	
Index	451

Advances in Robot Kinematics 2016

Lenarcic, J.; Merlet, J.-P. (Eds.)

2018, XII, 453 p. 201 illus., 131 illus. in color.,

Hardcover

ISBN: 978-3-319-56801-0